

VALLIAMMAI ENGINEERING COLLEGE

SRM NAGAR, KATTANKULATHUR – 603 203



PHYSICS PRACTICALS MANUAL

BS 8161- PHYSICS LABORATORY

(I Semester B.E/B.Tech. Courses for the Academic Year 2018-2019)

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(Private circulation only)

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DEPARTMENT OF PHYSICS

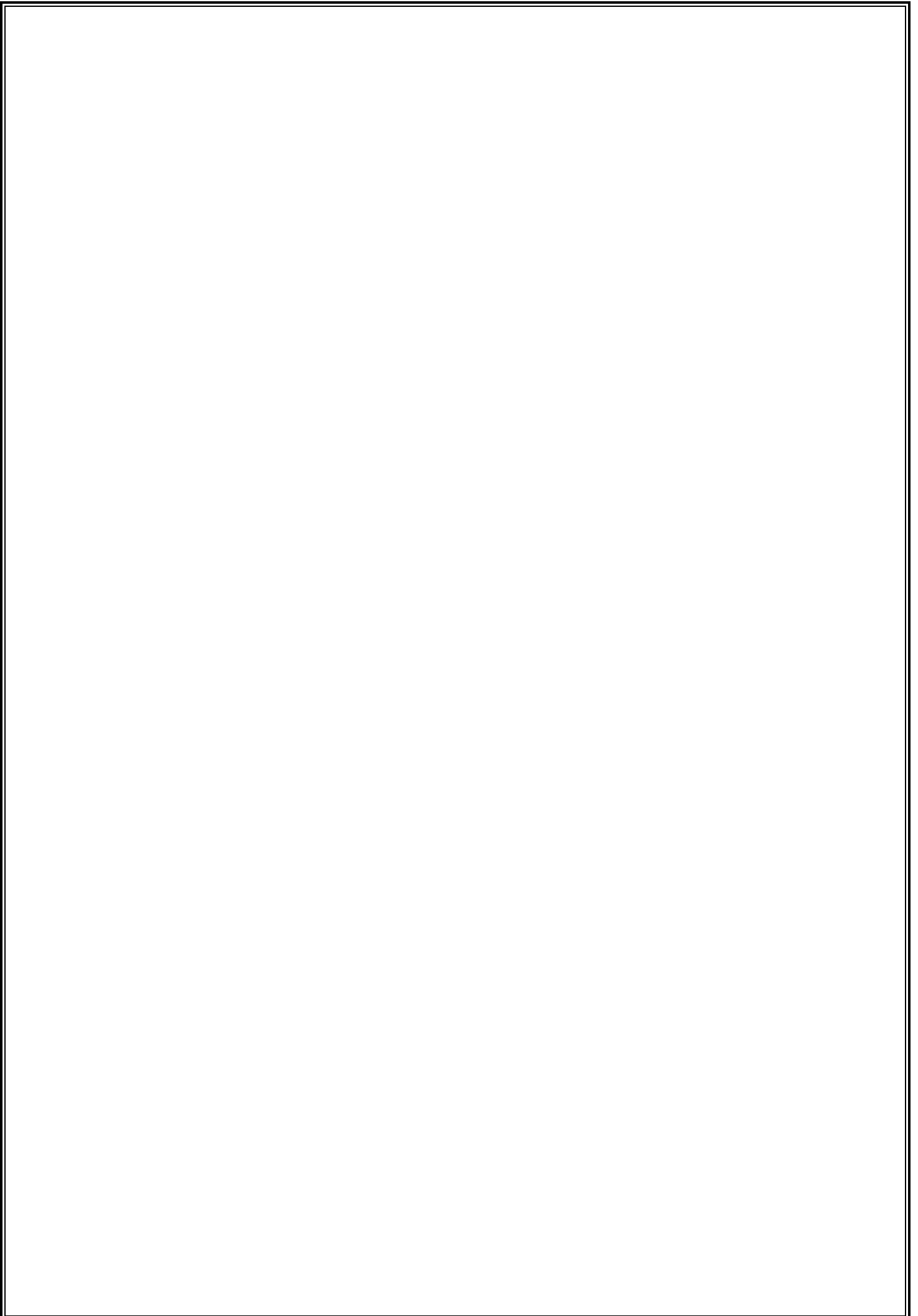
Instructions to the students

The following instructions must be followed by the students in their laboratory classes.

1. Students are expected to be punctual to the lab classes. If they are late, they will be considered absent for that particular session.
2. Students should strictly maintain the dress code.
3. Students must bring their observation note, record note (completed with previous experiment) and the calculator to every lab class without fail.
4. Students are advised to come with full preparation for their lab sessions by
 - (i) Reading the detailed procedure of the experiment from the laboratory manual.
 - (ii) Completion of observation note book (i.e.) Aim, Apparatus required, Formula (with description), least count calculation, diagrams and the tabular column should be written in the observation note before entering into the laboratory.
5. Data entry in the observation note book must be by pen only.
6. Students must get attestations immediately for their observed readings.
7. Students should complete their calculations for their experiments and get it corrected on the same day of that experiment.
8. Students who miss observation, record note they have to do the experiment once again and get it corrected.
9. Class assessment marks for each experiment is based only on their performance in the laboratory.
10. Record note has to be completed then and there and get corrected when the students are coming for the next lab class.
11. Students must strictly maintain silence during lab classes.
12. If any of the students is absent for the lab class for genuine reasons, he/she will be permitted to do the experiment during the repetition class only.
13. Students are advised to perform their experiments under safety care.
14. If any student is found causing damage to the lab equipments, he/she shall replace the same with a new.

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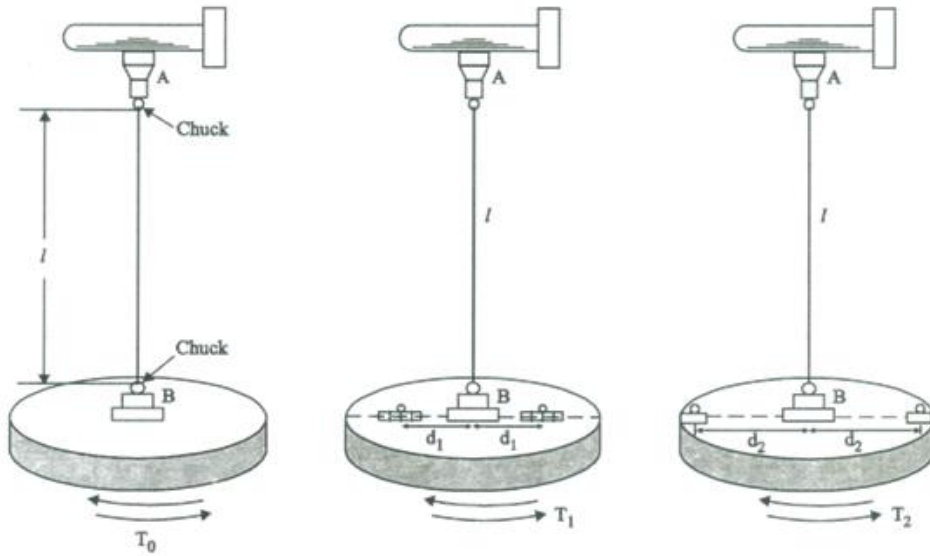


Fig.1.1. Torsional Pendulum

To find the time period of oscillations

Length of suspension wire $l = \dots\dots\dots$ cm

Position of equal masses	Time for 10 oscillations			Time period
	Trial 1	Trail 2	Mean	
Unit	second	second	second	second
Without masses				$T_0 =$
Masses at closest distance. $d_1 = \dots\dots\dots \times 10^{-2}$ m				$T_1 =$
Masses at maximum distance. $d_2 = \dots\dots\dots \times 10^{-2}$ m				$T_2 =$

1. DETERMINATION OF RIGIDITY MODULUS –TORSIONAL PENDULUM

AIM

To determine the moment of inertia of a given disc by Torsional oscillations and The rigidity modulus of the material of the suspension wire.

APPARATUS

Torsional pendulum, Stop clock, Meter scale, Two symmetrical mass, Screw gauge.

PRINCIPLE

The suspension wire is twisted by the circular disc fixed at the bottom of the wire and the wire undergoes shearing strain which leads to torsional oscillations. The angular acceleration of the disc is proportional to its angular displacement and is always directed towards its mean position and the motion of the disc is simple harmonic.

FORMULA

Moment of inertia of the circular disc,

$$I = \frac{2m(d_2^2 - d_1^2)T_0^2}{T_2^2 - T_1^2} \text{ kg.m}^2$$

Rigidity modulus of the wire,

$$n = \frac{8\pi l}{T_0^2 r^4} \text{ N/m}^2$$

Symbol	Explanation	unit
m	mass of one cylinder placed on the disc(100 gm)	kg
d ₁	Closest distance (minimum) between suspension wire and the centre of mass of the cylinder	m
d ₂	Farthest distance (maximum) between suspension wire and the centre of mass of the cylinder	m
T ₀	Period of oscillation without any mass on the disc	s
T ₁	Period of oscillation when equal masses are placed on the disc at a distance d ₁	s
T ₂	Period of oscillation when equal masses are placed on the disc at a distance d ₂	s
ℓ	length of the suspension wire	m
r	Radius of the wire	m

L

LEAST COUNT OF THE SCREW GAUGE:

$$\text{Pitch} = \frac{\text{Distance moved by the head scale on the pitch scale.}}{\text{Number of rotations given to the head scale.}}$$

$$\text{Least count (LC)} = \frac{\text{Pitch}}{\text{Total number of divisions on the head scale}}$$

Pitch = 5 mm/ 5 = 1 mm
 LC = 1 mm/ 100 = 0.01 mm.

To find the radius (r) of the specimen using screw gauge

LC = 0.01 mm

Z.E =div

Z.C =mm

S. No.	PSR	HSC	HSR= HSC x LC	Observed Reading = PSR + HSR	Correct Reading = OR + ZC
Unit	mm	div	mm	mm	mm

Mean (d) =----- x 10⁻³ m

Radius of the specimen wire (r) = d/2 = x 10⁻³ m

PROCEDURE

- When the suspension wire is twisted by the circular disc fixed at the bottom of the wire, the wire undergoes shearing strain. This is called torsion. Because of this torsion, the disc executes oscillation called torsional oscillation.
- The Torsional pendulum consists of a circular disc suspended by a thin suspended wire, as shown in Fig. (5.1), whose rigidity modulus is to be noted. The top end of the wire is fixed by a chuck. The circular disc is attached to the other end of the wire.

Calculation of T_0

- Adjust the wire so that its length is fixed value say 50 cm. Make a vertical chalk mark on the disc when it is rest as a reference. By making a small twist to the circular disc, set up Torsional oscillations. After the first few oscillations, just as the mark on the disc passes the equilibrium positions, a stop clock is started. The time taken for 10 complete oscillations is noted. The experiments are repeated for second trial and mean value is calculated. The mean value of the period is noted as T_0 .

Calculation of T_1

- The two identical cylindrical masses are placed at equal distance on either side of the central chuck as close as possible. The distance d_1 is measured between the wire and the centre of the cylindrical mass. By twisting the disc, the time taken for 10 complete oscillations is noted. The mean value of the time period is noted as T_1 .

Calculation of T_2

- The identical masses are arranged symmetrically as far away from the axis of the rotation as possible. The distance d_2 is measured between the centre of the cylindrical mass of the time taken for 10 complete oscillations is calculated in the same manner as that of the calculation of T_0 and T_1 .

Calculation of Moment Of Inertia and Rigidity Modulus

- The mean value of the radius and length of the wire is measured accurately by a screw gauge and meter scale respectively. The moment of the inertia of the circular disc and the rigidity modulus of the suspension wire are calculated by substituting the values in the equations respectively.
- Moment of Inertia can also be determined theoretically $I = MR^2$, where M= Mass of the Disc, R= radius of the Disc.

L

CALCULATION

Mean radius of the wire $r = \dots\dots\dots$ m

Length of the wire $\ell = \dots\dots\dots$ m

Mass of the identical cylinder $m = \dots\dots\dots$ kg

Closest distance between suspension wire & the centre of symmetrical mass $d_1 = \dots\dots\dots$ m

Farthest distance between suspension wire & the centre of symmetrical mass $d_2 = \dots\dots\dots$ m

Period of oscillations (without masses) $T_0 = \dots\dots\dots$ sec

Period of oscillations with masses at 'd₁' distance $T_1 = \dots\dots\dots$ sec

Period of oscillations with masses at 'd₂' distance $T_2 = \dots\dots\dots$ sec

The moment of inertia of the circular disc,

$$I = \frac{2m(d_2^2 - d_1^2)T_0^2}{T_2^2 - T_1^2} \text{ kg.m}^2$$

$$I = \dots\dots\dots \text{ kg/m}^2$$

Rigidity modulus of them wire,

$$\eta = \frac{8\pi I \ell}{T_0^2 r^4} \text{ N/ m}^2$$

$$\eta = \dots\dots\dots \text{ N/m}^2$$

RESULT

(i) Moment of inertia of the circular disc $I = \underline{\hspace{2cm}}$ kg m²

(ii) Rigidity modulus of the given wire $\eta = \underline{\hspace{2cm}}$ N/m²

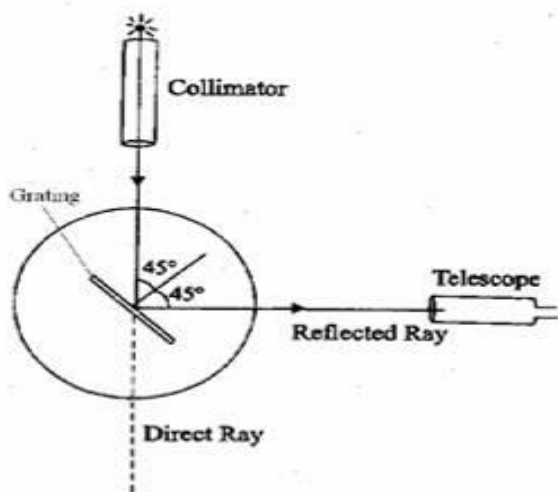


Figure 2.1. To set for normal incidence position

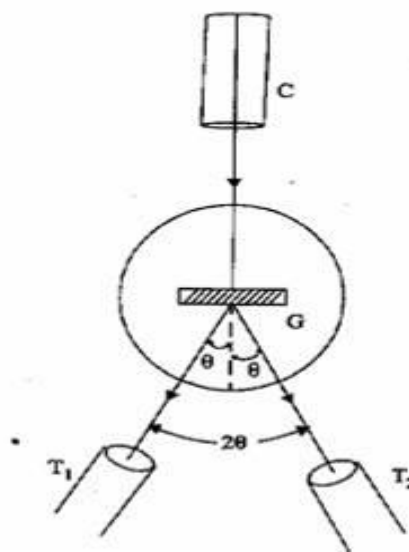


Figure 2.2. Diffracted ray from grating

DETERMINATION OF LEAST COUNT

$$2\text{MSD} = 1^\circ$$

$$1\text{MSD} = 1/2^\circ = 0.5^\circ = 30'$$

$$\text{LC} = 1 \text{ MSD} - 1 \text{ VSD}$$

Number of divisions in vernier scale = 30

$$30 \text{ VSD} = 29 \text{ MSD}$$

$$1 \text{ VSD} = 29/30 \times \text{MSD} = 29/30' \times 30' = 29'$$

$$\text{LC} = 30' - 29'$$

$$\text{LC} = 1' \text{ (One minute)}$$

2. SPECTROMETER - DETERMINATION OF WAVELENGTH OF MERCURY SPECTRUM

AIM

To determine the wavelength of the mercury (Hg) spectrum using the plane transmission grating.

APPARATUS REQUIRED

Spectrometer, Sodium vapour lamp, Plane transmission grating, spirit level, Mercury vapour lamp, and reading lens.

PRINCIPLE

A plane sheet of transparent material on which a large number of equidistant opaque rulings are made with a diamond point forms grating. The space between the rulings and transparent area constitute a parallel slit. When light passes through such a grating, diffraction takes place. Angle of diffraction depends upon the wavelength of the light and number of lines per metre on the grating. So the number of lines per metre in grating and wavelength of the source can be calculated.

FORMULA

The wavelength of the spectral lines of mercury spectrum

$$\lambda = \frac{\sin \theta}{n N} \text{ metre}$$

Symbol	Explanation	Unit
θ	Angle of diffraction	deg
N	Number of lines/ metre	lines/ metre
n	Order of spectrum	no unit



To determine the wavelength(λ) of the prominent lines of the mercury spectrum

Order of the spectrum $n = 1$
 $TR = MSR + (VSC \times LC)$

Least count = $1'$
 $N = \dots\dots\dots$ lines/meter

Spectral lines (colours)	Readings for diffracted image												Mean angle of diffraction θ	Mean 2θ	Difference between Vernier A and Vernier B		$\lambda = \frac{\sin \theta}{n N}$
	Left Side						Right side								$2\theta = A_1 \sim A_2 = B_1 \sim B_2$	deg.	
	Vernier A (A ₁)		Vernier B (B ₁)		Vernier A (A ₂)		Vernier B (B ₂)		2θ deg.	deg.							
	MSR	VSC	TR	MSR	VSC	TR	MSR	VSC			TR	MSR	VSC	TR	deg.	deg.	meter
Violet																	
Blue																	
Green																	
Yellow																	
Red																	

PROCEDURE

(i) Normal Incidence

Preliminary adjustments of the spectrometer are made. The grating is mounted on the grating table with its ruled surface facing the collimator the slit is illuminated by a source of light (sodium vapour lamp). The slit is made to coincide with the vertical cross wires. The vernier scales are adjusted to read 0° and 180° for the direct ray. The telescope is rotated through an angle of 90° and fixed. The grating table is adjusted until the image coincides with the vertical cross wire. Both the grating table and the telescope are fixed at this position as shown in Fig.2.1. Now rotate the vernier table through 45° in the same direction in which the telescope has been previously rotated. The light from the collimator incident normally on the grating. The telescope is released and is brought on the line with the direct image of the slit. Now the grating is said to be in normal incidence position

.

(iii) Determination of Wavelength (λ) of the Source

The sodium vapour lamp is replaced by mercury vapour lamp. The diffracted images of the first order are seen on either side of the central direct image as shown in Fig.2.2. The readings are tabulated by coincide the vertical cross wire with the first order on the either side of the central direct image prominent lines namely violet, blue, bluish green, green, yellow, red of the mercury spectrum. The difference between the readings give 2θ , from this θ can be found. The wavelength of each spectral line is calculated using the equation, $\lambda = \sin\theta / Nn$ metre.

L

CALCULATION

Order of the spectrum

$$n = 1$$

1. The wavelength of the spectral lines of mercury spectrum,

$$\lambda = \frac{\sin \theta}{n N} \text{ metre}$$

Wavelength for violet,

$$\lambda_v = \dots\dots\dots \text{\AA}$$

Wavelength for blue

$$\lambda_B = \dots\dots\dots \text{\AA}$$

Wavelength for green

$$\lambda_G = \dots\dots\dots \text{\AA}$$

Wavelength for yellow

$$\lambda_Y = \dots\dots\dots \text{\AA}$$

Wavelength for red

$$\lambda_R = \dots\dots\dots \text{\AA}$$

RESULT

- (i) Wavelength of various spectral lines

S.No	Colour of the spectrum	wavelength \AA
1	Violet	
2	Blue	
3	Green	
4	Yellow	
5	Red	

L

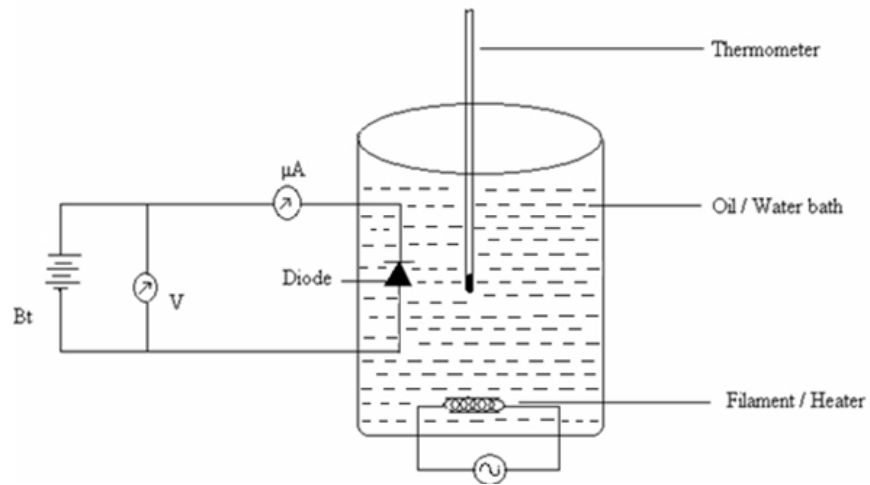


Fig.3.1. Circuit for band gap determination

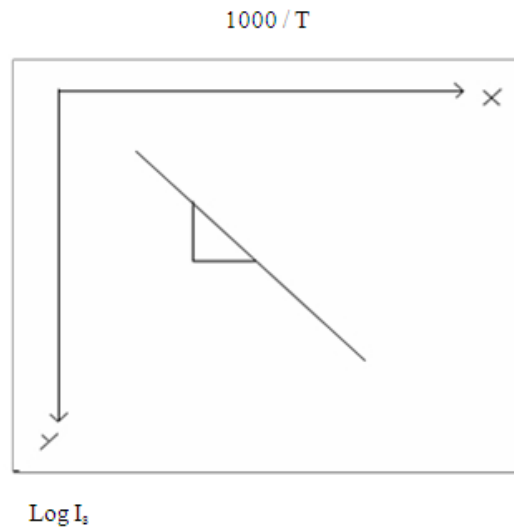


Fig.3.2. Variation of current with inverse temperature in a reverse biased pn -diode

3. DETERMINATION OF BAND GAP OF A SEMICONDUCTOR

AIM

To determine the band gap energy of a semiconductor by varying the temperature

APPARATUS REQUIRED

Semiconductor diode, Heating arrangement to heat the diode, Ammeter, Voltmeter, thermometer.

PRINCIPLE

For a semiconductor diode at 0K the valence band is completely filled and the conduction band is empty and it behaves as an insulator. If the temperature is increased, some of the valence electrons gains thermal energy greater than the forbidden energy (E_g) and it moves to conduction band, which constitutes some current to flow through the semiconductor diode.

FORMULA

$$\text{Band gap energy} \quad E_g = 0.198 \times \text{Slope} \quad \text{eV}$$

$$\text{Slope} = \log I_s / (1000/T)$$

Symbol	Explanation	Unit
I_s	Saturation current	μA
T	Absolute temperature	kelvin

PROCEDURE

- The circuit is given as shown in Fig.(1.1)
- The semiconductor diode and the thermometer is immersed in the water or oil bath, in such a way that the thermometer is kept nearby the diode.
- The power supply is kept constant (2Volts).
- The heating mantle is switched ON and the oil bath is heated up to 70°C.
- Now the heating mantle is switched OFF and the oil bath is allowed to cool slowly.
- For every five degree fall of temperature the micro ammeter the reading I_s is noted.

L

S.No	Temperature	Temperature	1000 /T	I_s	Log I_s
unit	°C	K	K⁻¹	x 10⁻⁶ A	
1					
2					
3					
4					
5					
6					
7					
8					
9					
10					

- A graph is plotted taking $1000/T$ along x axis and $\log I_s$ along negative y axis (Fig.3.2), (Since I_s in the order of micro-ampere, $\log I_s$ value will come in negative).
- A straight line obtained as shown in model graph.
- By finding the slope of the straight line, the band gap energy can be calculated using the given formula.

CALCULATION

$$E_g = 0.198 \times \text{Slope} \quad \text{eV}$$

$$E_g = 0.198 \times \log I_s / (1000/T) \quad \text{eV}$$

$$E_g = \dots\dots\dots \quad \text{eV}$$

RESULT

The band gap energy of the given diode is $E_g = \dots\dots\dots$ eV.

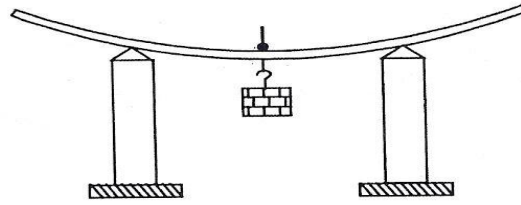


Figure 4.1 Young's modulus of the material – Non-uniform bending

DETERMINATION OF LEAST COUNT OF TRAVELLING MICROSCOPE

Least count = 1 MSD – 1 VSD

$$20 \text{ MSD} = 1 \text{ cm}$$

$$\text{Value of 1 MSD} = \frac{1}{20} \text{ cm} = 0.05 \text{ cm}$$

Number of Vernier Scale Division = 50

$$50 \text{ VSD} = 49 \text{ MSD}$$

$$1 \text{ VSD} = \frac{49}{50} \text{ MSD} = \frac{49}{50} \times 0.05 = 0.049$$

$$\text{LC} = 0.05 - 0.049 = 0.001 \text{ cm}$$

$$\text{LC} = 0.001 \text{ cm}$$

To find depression 'y'

Distance between two knife edges (l) = _____ $\times 10^{-2}$ m

$$\text{TR} = \text{MSR} + (\text{VSC} \times \text{LC})$$

$$M = \text{-----} \times 10^{-3} \text{ kg}$$

$$\text{L.C} = 0.001 \text{ cm}$$

S.No	Load	Microscope Readings						Mean	Depression Y for M kg
		Loading			Unloading				
		MSR	VSC	TR	MSR	VSC	TR		
Unit	$\times 10^{-3}$ kg	cm	div	cm	cm	div	cm	cm	cm
1	W								
2	W+50								
3	W+100								
4	W+150								
5	W+200								
Mean (y) = ----- $\times 10^{-2}$ m									

4. YOUNG'S MODULUS OF THE MATERIAL – NON-UNIFORM BENDING

AIM

To determine the young's modulus of the material of a uniform bar by non uniform bending method.

APPARATUS REQUIRED

Traveling microscope, Weight hanger with slotted weights, Two knife edges, Pin, Wooden bar, Vernier caliper, Screw gauge.

PRINCIPLE

When a beam symmetrically supported on two knife edge is loaded at its centre, the bent beam would not form an arc of circle. This type of bending is called non uniform bending. The maximum depression is produced at its mid point.

FORMULA

The Young's Modulus of the beam,

$$E = \frac{mgl^3}{4bd^3y} \text{ N/m}^2$$

Symbol	Explanation	Unit
M	Load applied	kg
l	Distance between the two knife edges	m
b	Breadth of the beam (meter scale)	m
d	Thickness of the beam (meter scale)	m
y	Depression produced for 'M' kg of load	m
g	Acceleration due to gravity	ms ⁻²

L

To find the thickness (d) of the beam using screw gauge

LC = 0.01 mm

Z.E = ± div

Z.C = ∓ mm

S. No.	PSR	HSC	HSR = HSC x LC	Observed Reading = PSR +HSR	Correct Reading = OR + ZC
Unit	mm	div	mm	mm	mm

Mean (d) = ----- x10⁻³ m

To find the breadth (b) of the beam using Vernier Calipers

LC = 0.01 cm

Z.E = ± div

Z.C = ∓ mm

S. No.	MSR	VSC	VSR = VSC x LC	Observed Reading = MSR +VSR	Correct Reading = OR +ZC
Unit	cm	div	cm	cm	cm

Mean (b) =----- x10⁻² m

PROCEDURE

The weight of the hanger is taken as the dead load ‘w’. The wooden bar is brought to elastic mood by loading and unloading it, a number of times with slotted weights. With the dead load w suspended from the midpoint, the microscope is adjusted such that the horizontal cross-wire coincides with the image of the tip of the pin. The reading in the vertical scale is taken.

The experiment is repeated by adding weights in steps of 50 gm each. Every time the microscope is adjusted and the vertical scale reading is taken. Then the load is decreased in the same steps and the readings are taken. From the readings, the mean depression of the mid-point for a given load can be found. The length of the wooden bar between the knife edges is measured (l).

The wooden bar is removed and its mean breadth ‘b’ and mean thickness ‘d’ are determined with a Vernier caliper and a screw gauge respectively.

From the observations, Young modulus of the material of the beam is calculated by using the given formula.

CALCULATION

- Acceleration due to gravity $g = 9.8 \text{ ms}^{-2}$
- Distance between the two knife edges $l = \dots\dots\dots \text{ m}$
- Breadth of the beam $b = \dots\dots\dots \text{ m}$
- Thickness of the beam $d = \dots\dots\dots \text{ m}$
- Depression produced for ‘M’ kg of load $y = \dots\dots\dots \text{ m}$
- Load to calculate depression $M = \dots\dots\dots \text{ kg}$

The Young’s modulus of the given material of the beam

$$E = \frac{mgl^3}{4bd^3y} \text{ N/m}^2$$

RESULT

The Young’s Modulus of the given wooden bar

$$E = \dots\dots\dots \text{ newton/meter}^2$$

L

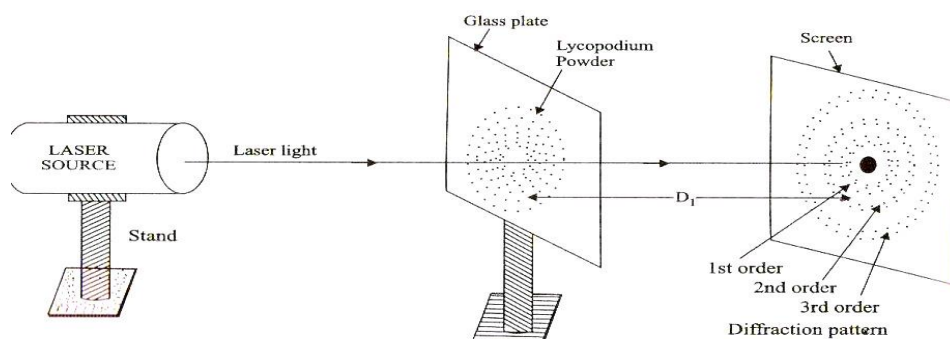


Figure 3.1 Laser Grating Experiment

Determination of wavelength of laser

Distance between the grating and the screen (D) =cm

Number of lines in grating per metre (N) = 1×10^5 lines / metre

S.No	Order of diffraction n	Readings of the diffracted image				$\lambda = \frac{\sin \theta}{nN}$	
		Distance of different Orders from the central spot		Mean $x = \frac{x_L + x_R}{2}$	$\tan \theta = \left(\frac{x}{D}\right)$		$\theta = \tan^{-1} \left(\frac{x}{D}\right)$
		Left side x_L	Right side x_R				
Unit		cm	cm	cm		(nm)	
1	1	$x_1 =$	$x_1 =$				
2	2	$x_2 =$	$x_2 =$				
3	3	$x_3 =$	$x_3 =$				
4	4	$x_4 =$	$x_4 =$				

5. (a) DETERMINATION OF WAVELENGTH OF THE GIVEN LASER**AIM:**

To determine the wavelength of the given laser using grating.

APPARATUS REQUIRED

Diode laser, grating, screen and scale.

PRINCIPLE

The laser light is exposed to the grating and diffraction takes place.

FORMULA

(1) Wavelength of the given laser

$$\lambda = \frac{\sin \theta}{nN} \text{ meter}$$

Symbol	Explanation	Unit
θ	Angle of diffraction	degree
N	Order of diffraction	-
N	Number of lines per meter in the grating	lines/m

PROCEDURE:

Diode laser is kept horizontally and switched on (care should be taken). The grating is held normal to the laser beam. This is done by adjusting the grating in such a way that the reflected laser beam coincides with the beam coming out of the laser. As shown in the Fig.3.1 After adjusting for normal incidence, the laser light is exposed to the grating and it is diffracted by it. On the other side of the grating on the screen, the diffracted laser spots are seen. The distances of different orders from the centre spot (x) are measured. The distance between the grating and screen (D) is measured. Using the formula ' θ ' is calculated. The wavelength of the laser light source is calculated using the given formula.

$$\lambda = \frac{\sin \theta}{Nn} \text{ metre}$$

The number of lines in the grating is assumed as $\approx 1 \times 10^5$ lines per metre.

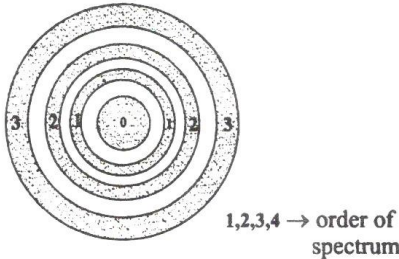


Figure 4.2. Particle size determination by Laser

Particle size determination

S.No	Distance between screen and glass plate (D)	Order of diffraction n	Distance between the central bright point and n th fringe X _n	Particle Size $d = \frac{n\lambda D}{Xn}$
Unit	cm		cm	cm
1		1		
		2		
2		1		
		2		
Mean d =				

PARTICLE SIZE DETERMINATION USING LASER**AIM**

To determine the size of the given micro particles (lycopodium powder) using laser.

APPARATUS REQUIRED

Diode laser, fine micro particles having nearly same size, glass plate, screen, metre scale

FORMULA

Particle size (diameter) d is given by

$$d = \frac{n\lambda D}{x_n} \text{ metre}$$

Symbol	Explanation	Units
n	Order of diffraction	-
λ	Wavelength of laser light used	metre
D	Distance between glass plate and the screen.	metre
x_n	Distance between central bright spot and the n^{th} ring	metre

PROCEDURE

A glass plate is taken and a fine powder of particle size in the range of micrometer is sprinkled on the glass plate. This glass plate is kept between laser light and screen. The experimental is shown in the Fig.4.2. Now laser beam gets diffracted by the particles present in the glass plate. By adjusting the distance between the glass plate and the screen, (D) a circular fringe pattern is seen on the screen and the distance between the central bright point and n^{th} fringe x_n for various orders of diffraction is measured.

Using the formula, the particle size is determined. The experiment is repeated for different D values.

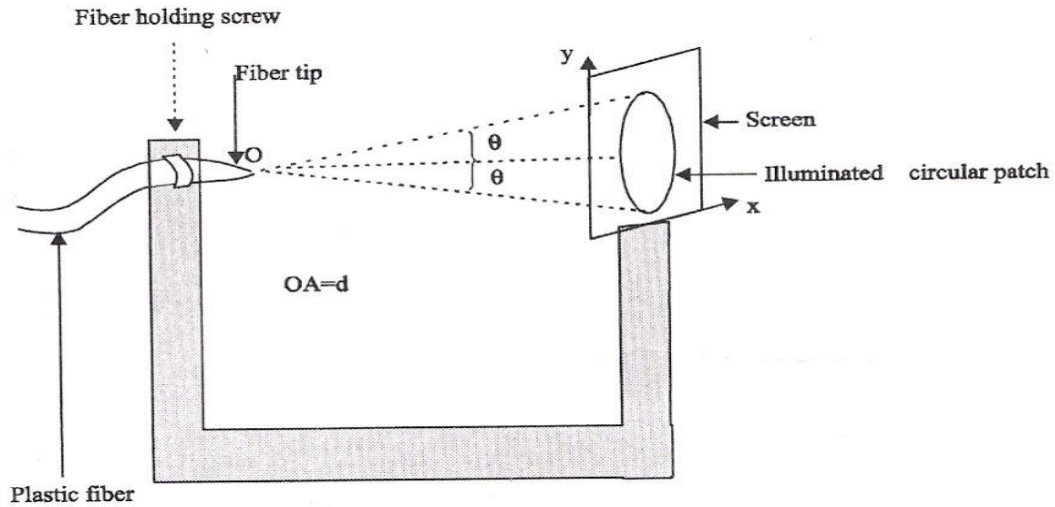


Figure 4.3. Experimental setup for acceptance angle

To determine acceptance angle

S.No	Distance from the fiber end to circular image 'd'	Radius of the circular image 'r'	Acceptance angle $\theta_a = \frac{r}{d} \times \frac{180}{\pi}$
Unit	cm	mm	deg.
1			
2			
3			
4			

(b) DETERMINATION OF ACCEPTANCE ANGLE IN AN OPTICAL FIBRE

AIM

To determine acceptance angle of an optical fiber.

APPARATUS REQUIRED

Laser for optical fiber light source, optical fiber, optical fiber connectors and Numerical aperture Jig.

PRINCIPLE

The principle behind the transmission of light waves in an optical fiber is total internal reflection.

FORMULA

$$\text{Acceptance angle } \theta_a = \frac{r}{d} \times \frac{180}{\pi} \text{ deg}$$

Symbol	Explanation	Unit
r	Radius of the circular image	metre
d	Distance from fibre end to circular image	metre

PROCEDURE

Using laser, we can find the acceptance angle of the fiber optic cable. The given laser source is connected to the optical fiber cable. The other end is exposed to the air medium in the dark place. The emerging light is exposed on a plain paper.

Now, we get illuminated circular patch on the screen. Fig.3.3 shows the experimental setup for acceptance angle measure. The distance from the fiber end to circular image (d) is measured using meter scale. The radius of the circular image is also measured. Thus the acceptance angle is calculated

CALCULATION

(i) Wavelength of the laser source,

$$\lambda = \frac{\sin \theta}{nN} \text{ metre}$$

(ii) The size of the particle,

$$d = \frac{n\lambda D}{x_n} \text{ metre}$$

(iii) Acceptance angle,

$$\theta_a = \frac{r}{d} \times \frac{180}{\pi} \text{ deg}$$

RESULTS

- i) Wavelength of the given source $\lambda =$ ----- metre.
- ii) The size of the particle $d =$ _____ m
- iii) Acceptance angle $\theta_a =$ _____ degree.

L

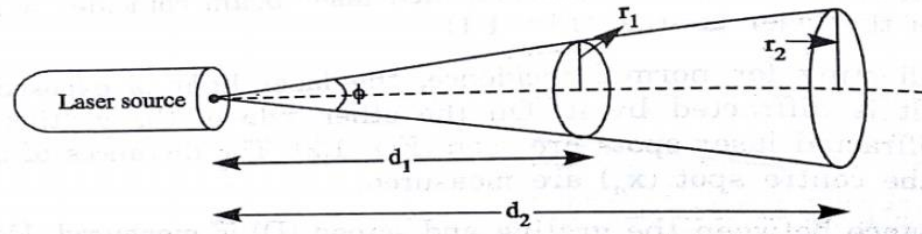


Fig. 6.1 Angle of divergence

Determination of angle of divergence

S.No	r_1	r_2	d_1	d_2	$\phi = \frac{r_2 - r_1}{D_2 - D_1} \times \frac{180}{\pi}$
Unit	m	m	m	m	degree

EXPERIMENT BEYOND SYLLABUS

6. DETERMINATION OF ANGLE OF DIVERGENCE

AIM

To determine the Angle of Divergence of the given laser light.

APPARATUS

Laser source , screen and meter scale.

FORMULA

Angle of Divergence

$$\phi = \frac{r_2 - r_1}{D_2 - D_1} \times \frac{180}{\pi} \text{ degrees}$$

Symbol	Explanation	Unit
r_1	Radius of the beam spot at the distance d_1	metre
r_2	Radius of the beam spot at the distance d_2	metre

PROCEDURE

The angle of divergence gives the angular spread of the laser beam . A diagrammatic explanation of finding the angle of divergence is shown Fig 6.1.

Here the laser source and a stand is kept at a distance say d_1 and the radius of the beam spot is measured .Now, by varying the distance to d_2 , the radius of the beam spot is again measured. Substituting these values in the given formula, the angle of divergence can be calculated. The experiment is repeated for various values of d_1 and d_2 and the mean angle of divergence is determined.

DATA OF PHYSICAL CONSTANTS & STANDARD VALUES

S.No.	Physical Constants	Symbol	Value in SI Unit
1	Velocity of light	C	3×10^8 m/s
2	Acceleration due to gravity	g	9.8 m/s ²
3	Planck's constant	h	6.625×10^{-34} Js
4	Charge of an electron	e	1.69×10^{-19} C
5	Avogadro number	N _A	6.023×10^{26} atoms/ k mole
6	Boltzmann constant	k	1.38×10^{-23} J/K
7	Young's modulus of the wooden beam	E	1×10^{10} Nm ⁻²
8	Young's modulus of the teak wooden beam	E	1.7×10^{10} Nm ⁻²
9	Wavelength of sodium vapour lamp	λ	D ₁ = 5890 Å, D ₂ = 5896 Å
10	Wavelength of mercury vapour lamp	λ_V λ_B λ_G λ_{YI} λ_R	4047 Å 4358 Å 5461 Å 5770 Å 6234 Å

VIVA QUESTIONS AND ANSWERS

RIGIDITY MODULUS- TORSIONAL PENDULUM

1. What is torsional pendulum?

A body suspended from a rigid support by means of a long and thin elastic wire is called torsional pendulum.

2. What is the type of oscillation?

This is of simple harmonic oscillation type.

3. How will you determine the rigidity of fluids?

As fluids do not have a shape of their own, hence they do not possess rigidity. Hence there is no question of determining it.

YOUNG'S MODULUS NON-UNIFORM BENDING

1. What is young's modulus?

Young's modulus is defined as the ratio of longitudinal stress to longitudinal strain.

2. What is a beam?

When the lengths of the rod of uniform cross section is very large compared to its breadth such that the shearing stress over any section of the rod can be neglected, the rod is called beam.

3. How are longitudinal strain and stress produced in your experiment?

Due to depression, the upper or the concave side of the beam becomes smaller than the lower or the convex side of the beam. As a result, longitudinal strain is produced. The change in wave length of the beam. These forces will give rise to longitudinal stress.

4. Which dimension- breadth, thickness or length of the bar-should be measured very careful and why?

The thickness of the bar should be measured very carefully since its magnitude is small and it occurs in the expression 'E' in the power of three. An inaccuracy in the measurement of the thickness will produce the greatest proportional error in 'E'.

5. Why do you place the beam symmetrically on the knife edges?

To keep the reaction at the knife edges equal in conformity with the theory.

LASER PARAMETERS

1. Define LASER?

The term LASER stands for Light Amplification by Stimulated Emission of Radiation. It is a device which produces a powerful, monochromatic collimated beam of light in which the waves are coherent.

2. What is meant by active material in laser?

The material in which the population inversion is achieved is called active material.

3. What is semi conductor diode laser?

Semiconductor diode laser is a specially fabricated pn junction diode. It emits laser light when it is forward biased.

4. What are the characteristic of laser radiation?

Laser radiations have high intensity, high coherence, monochromatic and high directionality with less divergence.

5. What is stimulated emission?

The process of forced emission of photons caused by incident photons is called stimulated emission

6. Define acceptance angle

The maximum with which a ray of light can enter through one end of the fiber and still be totally internally reflected is called acceptance angle of the fiber.

7. What is the principle used in fiber optic communication system?

The principle behind the transmission of light waves in an optical fiber is total internal reflection

BAND GAP OF A SEMICONDUCTOR

1. Define Fermi level

Fermi level is that state at which the probability of electron occupation is $\frac{1}{2}$ at any temperature above 0K and also it is the level of maximum energy of the filled states at 0K.

2. What are intrinsic and extrinsic semiconductors?

Intrinsic semiconductors are semiconductors in pure form. A semiconducting material in which charge carriers originate from impurity atoms added to the material is called an extrinsic semiconductor.

SPECTROMETER GRATING

1. What is the use of collimator and telescope?

A collimator is a device that narrows a beam of particles or waves. A telescope is an instrument that aids in the observation of remote objects by collecting electromagnetic radiation (such as visible light).

2. What is plane transmission diffraction grating?

A plane transmission diffraction grating is an optically plane parallel glass plate on which equidistant, extremely close grooves are made by ruling with a diamond point.

3. In our experiment. What class of diffraction does occur and how?

Fraunhofer class of diffraction occurs. Since the spectrometer is focused for parallel rays, the source and the image are effectively at infinite distances from the grating.

4. How are the commercial gratings made?

A commercial grating is made by pouring properly diluted cellulose acetate on the actual grating and drying it to a thin strong film. The film is detached from the original grating and is mounted between two glass plates. A commercial grating is called a replica grating. In our experiment we use a plane type replica grating.