SRM VALLIAMMAI ENGINEERING COLLEGE

(An Autonomous Institution) SRM Nagar, Kattankulathur – 603 203

DEPARTMENT OF ARTIFICIAL INTELLIGENCE & DATA SCIENCE

QUESTION BANK



IV SEMESTER

AD3461 – ARTIFICIAL INTELLIGENCE - I

Regulation – 2023

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Prepared by

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DEPARTMENT OF ARTIFICIAL INTELLIGENCE & DATA SCIENCE

OUESTION BANK

SUBJECT : AD3461 – Artificial Intelligence - I YEAR/SEM : II Year / IV Semester

UNITI INTELLIGENT AGENT

Introduction to AI - Agents and Environments - Concept of Rationality - Nature of Environments -

Structure of Agents – Problem Solving Agents – Search Algorithms – Uninformed Search Strategies.

	PART – A			
Q.No	Questions	BT	Competence	
		Level		
1	Define an agent.	BTL1	Remember	
2	Define Artificial Intelligence (AI).	BTL1	Remember	
3	What is the role of agent program?	BTL1	Remember	
4	What are the components that define a problem in Artificial Intelligence?	BTL1	Remember	
5	What is an agent function? Differentiate an agent function and an agent program.	BTL1	Remember	
6	What is meant by Turing test?	BTL1	Remember	
7	State the concept of rationality.	BTL1	Remember	
8	Give the structure of agent in an environment.	BTL1	Remember	
9	List some of the uninformed search techniques.	BTL1	Remember	
10	What are the steps involved to solve a problem in AI?	BTL1	Remember	
11	List the properties of task environments.	BTL1	Remember	
12	What is a task environment? How is it specified?	BTL1	Remember	
13	Why problem formulation must follow goal formulation?	BTL2	Understand	
14	List down the characteristics of intelligent agent.	BTL2	Understand	
15	What are the factors that a rational agent should depend on at any	BTL2	Understand	
	given time?			
16	Differentiate between Intelligence and Artificial Intelligence.	BTL2	Understand	
17	Give the general model of a learning agent.	BTL2	Understand	
18	Compare Deterministic vs Stochastic environment.	BTL2	Understand	
19	Give PEAS description for Part picking robot.	BTL2	Understand	
20	Give performance evaluation measure for BFS, DFS, UCs, IDDFS, DLS.	BTL2	Understand	
21	Characterize the environment of an agent playing soccer.	BTL2	Understand	

always be perfectly rational? For each of the environment below determine what type of agent	BTL2	Understand
	BTL2	Understand
	1	Unucistanu
architecture is most appropriate (table lookup, simple reflex, goal-		
based or utility-based).		
a) Medical Diagnosis System		
b) Satellite Image Analysis System		
c) Part Picking Robot		
d) Interactive English Tutor		
Formulate PEAS for an automated taxi driver.	BTL2	Understand
PART-B		1
Explain the architecture of an intelligent agent. Include a diagram to	BTL3	Apply
		11.2
	BTL3	Apply
(1)	2120	
states will be visited usin <mark>g (1) breadth fir</mark> st search (2) depth		
first search (3) depth limited search with a limit 2 (depth of the		
root is 0) (4) Iterative deepening search. (8)		
ii. If iterative deepening search is used to traverse the state space,		
how many times will the state space tree be constructed to		
reach the goal. (4)		
iii. If bidirectional search is used to reach the goal state, what		
would be the branching factor in the forward and backward		
direction? (4)		
Explain the structure of a typical intelligent agent with an example.	BTL3	Apply
Discuss how the structure influences the agent's performance. (16)		
Perform BFS, DFS, Uniform Cost Search strategies on the following	BTL3	Apply
5		
3 3 3 2		
S 5 F 5		
G H G		
5		
Explain the concept of rationality in AI agents and analyze how it	BTL3	Apply
	 c) Part Picking Robot d) Interactive English Tutor Formulate PEAS for an automated taxi driver. PART-B Explain the architecture of an intelligent agent. Include a diagram to illustrate the components and their interactions. (16) Consider a state space given below. i. If the goal state is numbered '11', list the order in which the states will be visited using (1) breadth first search (2) depth first search (3) depth limited search with a limit 2 (depth of the root is 0) (4) Iterative deepening search. (8) ii. If iterative deepening search is used to traverse the state space, how many times will the state space tree be constructed to reach the goal. (4) iii. If bidirectional search is used to reach the goal state, what would be the branching factor in the forward and backward direction? (4) Explain the structure of a typical intelligent agent with an example. Discuss how the structure influences the agent's performance. (16) Perform BFS, DFS, Uniform Cost Search strategies on the following graph and also formulate the algorithm. (16) 	 c) Part Picking Robot d) Interactive English Tutor Formulate PEAS for an automated taxi driver. BTL2 PART-B Explain the architecture of an intelligent agent. Include a diagram to illustrate the components and their interactions. (16) Consider a state space given below. a state space given below. BTL3 a state space given below. b TL3 a state space given below. a state space given below. b TL3 a state space given below. b TL3 c a state space given below. c a state space given below. b TL3 c a state space for a typical intelligent agent with an example. D Discuss how the structure of a typical intelligent agent with an example. D Discuss how the structure of a typical intelligent agent with an example. D Discuss how the structure of a typical intelligent agent with an example. D Discuss how the structure influences the agent's performance. (16) Perform BFS, DFS, Uniform Cost Search strategies on the following graph and also formulate the algorithm. (16) c a structure influences the agent's performance. (16) D Discuss how the structure influences the agent's performance. (16) D Discuss how the structure influences the agent's performance. (16) D Discuss how the structure influences the agent's performance. (16) D Discuss how the structure influences the agent's performance. (16) D Discuss how the structure influences the agent's performance. (16) D Discuss how the structure influences the agent's performance. (16) D Discuss how the structure influences the agent's performance. (16) D Discuss how the structu

6	Describe the structure of a Goal-Based Agent and explain how it differs from a simple reflex agent. Analyze the implications of these differences in a dynamic environment	BTL3	Apply
7	differences in a dynamic environment.	DTI 2	A
7	Describe the components necessary to define a problem in AI and	BTL3	Apply
	discuss how each component contribute to the problem-solving		
8	process. (16) Consider the water jug problem: You are given two jugs, a 4 gallon	BTL3	Apply
0	one and 3-gallon one. Neither has any measuring marker on it. There	DILJ	Арріу
	is a pump that can be used to fill the jugs with water. How can you get		
	exactly 2 gallon of water from the 4-gallon jug? Explain the state		
	space representation and apply an optimal sequence of actions to solve		
	it. (16)		
9	Describe the PAES representation for an automated taxi driver, an	BTL4	Analyze
	ATM system, and a medical diagnosis system. Explain each		
	component in the context of the agents. (16)		
10	What is an Intelligent agent? Define and explain the terms percept,	BTL4	Analyze
	percept sequence, agent function, and agent program using the		· ·
	vacuum cleaner example. (16)		
11	Define an agent. Explain the four basic agents that embody the	BTL4	Analyze
	principles underlying intelligent systems with examples. (16)		
12	Explain in detail the uninformed search strategies: Breadth-First	BTL4	Analyze
	Search (BFS), Depth-First Search (DFS), and Uniform Cost Search		
	(UCS). Provide a comparison of their working principles, advantages, and limitations. (16)		
13	List the basic kinds of intelligent agents and explain any two agents	BTL4	Analyze
	with neat schematic diagram. (16)		· ·
14	Explain the concept of the Turing Test and analyze its relevance in	BTL4	Analyze
	evaluating AI systems. Discuss it advantages and disadvantages as a		
	measure of intelligence. (16)		
15	What is an Agent? How does it interact with environment? Explain.	BTL4	Analyze
	(6)		
	What is informed search technique? Explain any one in detail. (10)		
16	Explain in detail the uninformed search strategies: Depth-First Search	BTL4	Analyze
	(DFS), Iterative Deepening Depth-First Search (IDDFS), and Depth-	-	
	Limited Search (DLS). Discuss their methodologies, applications, and		
	limitations. (16)		
17	Explain the differences between Uninformed Search and Informed	BTL4	Analyze
	Search algorithms, and analyse their effectiveness in a specific		
	problem-solving scenario. (16)		

UNIT II PROBLEM SOLVING

Informed (Heuristic) Search Strategies – Heuristic Functions – Local search and optimization problems – Local search in continuous space – Search with non-deterministic actions – Search in partially observable environments – Online search agents and unknown environments.

	PART – A				
Q.No	Questions	BT Level	Competence		
1	Define Greedy BFS.	BTL1	Remember		
2	List the various search strategies.	BTL1	Remember		
3	List the various informed search strategies.	BTL1	Remember		
4	Define A* search.	BTL1	Remember		
5	What is Recursive BFS?	BTL1	Remember		
6	What is local search?	BTL1	Remember		
7	Define Global minimum and Global maximum.	BTL1	Remember		
8	Define annealing.	BTL1	Remember		
9	What is an online search agent?	BTL1	Remember		
10	Give the procedure of IDA* search.	BTL1	Remember		
11	What is heuristic search strategy?	BTL1	Remember		
12	What is the advantage of heuristic function?	BTL1	Remember		
13	Define the effect of heuristic accuracy on performance.	BTL2	Understand		
14	What is the use of online search agent? RM	BTL2	Understand		
15	Differentiate greedy search and A* search.	BTL2	Understand		
16	Define admissible and dominant heuristics.	BTL2	Understand		
17	What do you mean by local maxima with respect to search technique.	BTL2	Understand		
18	Define Hill climbing search.	BTL2	Understand		
19	Define variants of hill climbing search.	BTL2	Understand		
20	State the reason when hill climbing often gets stuck.	BTL2	Understand		
21	What is the purpose of a contingency plan?	BTL2	Understand		
22	Compare and contrast admissible and consistent heuristics.	BTL2	Understand		
23	What is Heuristic Function?	BTL2	Understand		
24	What are the things that agents know in online search problem?	BTL2	Understand		
	PART-B		•		
1	Explain the working of hill climbing algorithm with suitable example.	BTL3	Apply		
	(16)				
2	Explain various local search algorithm in detail. (16)	BTL3	Apply		
3	Explain various informed or heuristic search technique in detail. (16)	BTL3	Apply		
4	Explain how you would implement a heuristic function for a specific	BTL3	Apply		
	problem, such as the 8-puzzle problem. (16)				
5	Discuss on Online Search Agents that uses depth-first exploration. (16)	BTL3	Apply		
6	Describe how you would use the Best-First Search algorithm to navigate a maze. (16)	BTL3	Apply		

7	Outline A* Algorith from Lugoj to Bud Show the sequence lines distance is give 75 75 75 75 110 118 118 118 118 1000 70 1000 70 1000 100	charest usin of nodes tr en below. (Stolu 99 F 80 Rimnicu Vite 97	agaras Pitesti 211 38 9 Tree Columnations of the straight-line aversed by the algo 16) Nearnt 87 Bacharest 90	distance heuristic. orithm. The straight		Apply
1	Town	Air Dist.	Town	Air Dist.		
	Arad	366	Mehadia	241		
	Bucharest	0 🍼	Neamt	234		
	Craiova	160	Oradea RM	380		
	Dobreta	242	Pitesti	100		
	Eforie	161	Rimnicu Vilcea	193		
	Fagaras	176	Sibiu	253		
	Giurgiu	77	Timisoara	329		
	Hirsova	151	Urziceni	80		
	Lasi	226	Vaslui	199		
	Lugoj	244	Zerind	374		
8	Consider the follow and a goal state. Ou and place it in ord moves either left, n convert the current puzzle. Explain pro	r task is to er followed right, up or / start state	slide the tiles of the in the goal state. down. There can to the goal state, s	current / start state There can be four be several ways to		Apply
	II	nitial Stat	e Goal Sta	te		
		23		1		
				<u> </u>		
	3	3 4	4 4 4	3		
		7 6 5	5 7 6	5		
				<u> </u>		
9	Explain in detail ab	out A* algo	orithm with suitable	example. (16)	BTL4	Analyze
10	Explain in details a	bout varian	ts of A* algorithm.	(16)	BTL4	Analyze

11	Explain the types of hill climbing techniques. (16)	BTL4	Analyze
12	Explain the performance of online search algorithm in an unknown	BTL4	Analyze
	environment. (16)		
13	Discuss Greedy BFS and Recursive BFS with suitable example in	BTL4	Analyze
	detail. (16)		
14	Discuss how searching is done in non-deterministic and partially	BTL4	Analyze
	observable environment. (16)		
15	i. What is heuristic search technique in AI? How does heuristics	BTL4	Analyze
	search works? Explain its advantages and disadvantages. (8)		
	ii. Describe the local search algorithm with neat sketch (8)		
16	i. Explain the steps involved in formulating problems with	BTL4	Analyze
	example. (10)		
	ii. Write a short note on genetic algorithm. (6)		
17	Elaborate on the need for local search algorithms and discuss any one	BTL4	Analyze
	algorithm in detail. (16)		

	UNIT III GAME PLAYING AND CSP				
Game	Game theory – Optimal decisions in games – Alpha-beta search – Monte-Carlo tree search – stochastic				
	- Partially observable games - Constraint Satisfaction Problems - C				
Backtr	acking search for CSP – Local Search for CSP – Structure of CSP.				
	Z PART – A				
Q.No	Questions	BT	Competence		
		Level			
1	What is a game?	BTL1	Remember		
2	What is Nash equilibrium?	BTL1	Remember		
3	What is a game tree?	BTL1	Remember		
4	What is a ply in game tree?	BTL1	Remember		
5	What is minimax algorithm?	BTL1	Remember		
6	What is alpha beta pruning?	BTL1	Remember		
7	What is constraint satisfaction Problem.	BTL1	Remember		
8	Define forward checking and backtracking in CSP.	BTL1	Remember		
9	Give applications of game theory.	BTL1	Remember		
10	What are stochastic games?	BTL1	Remember		
11	How alpha beta pruning overcome the drawback of minimax	BTL1	Remember		
	algorithm?				
12	List the types of constraints in CSP.	BTL1	Remember		
13	What do you mean by constrain propagation?	BTL2	Understand		
14	How do we represent the structure of problems in CSP.	BTL2	Understand		
15	Define Cycle Cutset.	BTL2	Understand		
16	List the types of assignments in CSP.	BTL2	Understand		
17	What is Tree Decomposition.	BTL2	Understand		

18	Define Conflict directed backjumping	BTL2	Understand
19	How can minimax also be extended for game of chance.	BTL2	Understand
20	 Define MRV and LCV in CSP. i. Minimum remaining values heuristic chooses the variable with the fewest "legal" values. ii. Least constraining value heuristic prefers the value that rules 	BTL2	Understand
	out the fewest choices for the neighboring variables in the constraint graph.		
21	Justify why we cannot use traditional min max for games with an element of chance, such as backgammon.	BTL2	Understand
22	Write the components of a game.	BTL2	Understand
23	Give a precise formulation of the following constraint satisfaction problem in terms of variable, domain and constraints: There are five professors and 10 classrooms, a list of classes to be offered, and a list of possible time slots for each class. Each professor has a set of classes that he or she can teach.	BTL2	Understand
24	In the game tree given below, \triangle represents Max node, \bigtriangledown represents Min node and o represents chance nodes, Find the utility value of the root node.	BTL2	Understand
	PART-B		
1	Describe about Constraint Satisfaction Problem with an algorithm for solving cryptoaritmetic problem. (16)	BTL3	Apply
2	How minmax procedure can be modified to play multiplayer games in detail. (16)	BTL3	Apply
3	Consider the map coloring problem with 6 variables and three colors (red, green, blue). The constraint graph for the problem is given below. How does backtracking search solve the given problem? What are the heuristics used to improve the efficiency of the search? How are failures detected early in backtracking? Can Breadth First Search be applied to the above problem? State reasons for your answer. (16)	BTL3	Apply

4	Consider the following game tree in which the static scores (in	BTL3	Apply
	parentheses at the tip nodes) are all from the first players point of view.		
	Assume that the first player is the maximizing player.		
	A		
	$\land \land \land \land \land \land \land \land$		
	L M N O P Q R S T U V W X Y (2) (3) (8) (5) (7) (6) (0) (1) (5) (2) (8) (4) (10) (2)		
	Which move should the first player choose? Use minmax algorithm on		
	the game tree and list the nodes which would not be examined using		
	the alpha-beta algorithm assuming that nodes are examined in left-to- right order? Will the same branches be pruned if the nodes are		
	examined in right-to-left order? Is alpha-beta algorithm guaranteed to		
	force a win whenever possible? State reasons. (16)		
5	Explain minmax game playing algorithm in detail with suitable	BTL3	Apply
	example. (16)		
6	Explain alpha beta pruning in detail with an example. (16)	BTL3	Apply
7	Explain in detail about constraint propagation. (16)	BTL3	Apply
8	Discuss about backtracking in constraint satisfaction problem. (16)	BTL3	Apply
9	What are partially observable games? How are they solved in a	BTL4	Analyze
10	deterministic environment? (16)		
10	Brief on map-coloring problem as CSP and explain with an example.	BTL4	Analyze
11	(16)	DTI 4	A 1
11	Brief on Min-Max algorithm and also discuss the need for alpha-beta	BTL4	Analyze
12	pruning. (16)	DTI 4	Analyza
12	Explain the constraint satisfaction problem and the variations on constraint satisfaction problem with example. (16)	BTL4	Analyze
13	i. Write short notes on Monte-Carlo search. (6)	BTL4	Analyze
15	ii. Define local consistency. What are the different types of local	DILA	Anaryze
	consistency? Explain anu two.		
14	i. How does alpha beta search algorithm differ from Minmax	BTL4	Analyze
	algorithm. Analyze. (6)		J
	ii. Explain the concept of game theory and its role in artificial		
	intelligence. Discuss the process of making optimal decisions		
	in games with suitable example. (10)		
15	Briefly describe the structure of problem in constraint satisfaction	BTL4	Analyze
	problem. (16)		
16	Explain in detail about local search in constraint satisfaction problem,	BTL4	Analyze
	(16)		
17	What are stochastic games? Explain their characteristics and strategies	BTL4	Analyze
	for decision-making with examples. (16)		

UNIT IVLOGICAL AGENTSKnowledge-based agents – Propositional logic – Propositional theorem proving – Propositional modelchecking – Agents based on propositional logic – First-order logic – Syntax and semantics –Knowledge representation and engineering – Inferences in first-order logic – Forward chaining –Backward chaining – Resolution.

	PART – A		
Q.No	Questions	BT Level	Competence
1	What is a Knowledge-Based Agent?	BTL1	Remember
2	What is Horn clause and Definite Clause?	BTL1	Remember
3	Name two standard quantifiers.	BTL1	Remember
4	What are the limitations in using propositional logic to represent a knowledge base?	BTL1	Remember
5	What is the purpose of unification?	BTL1	Remember
6	Define meta rules.	BTL1	Remember
7	Define atomic and complex sentences.	BTL1	Remember
8	Define first-order definite clause.	BTL1	Remember
9	State the generalized modus ponens.	BTL1	Remember
10	What is Skolemisation?	BTL1	Remember
11	List various inference rules in propositional logic.	BTL1	Remember
12	List various inference rules in predicate logic.	BTL1	Remember
13	What is resolution?	BTL2	Understand
14	Give the grammar to represent propositional logic.	BTL2	Understand
15	Give the grammar to represent predicate logic.	BTL2	Understand
16	Distinguish between propositional logic and predicate logic.	BTL2	Understand
17	Differentiate forward and backward chaining.	BTL2	Understand
18	Represent the following sentence in predicate form: "All the children like sweets."	BTL2	Understand
19	Define causal and diagnostic rules with an example.	BTL2	Understand
20	What factors justify whether reasoning is to be done in forward or backward reasoning?	BTL2	Understand
21	State the converse and contrapositive of the statement "when I stay up late, it is necessary that I sleep until noon".	BTL2	Understand
22	Define the terms belief state and state estimation.	BTL2	Understand
23	Some people like every vegetable. Convert it to First order logic.	BTL2	Understand
24	What are the three levels in describing knowledge-based agent?	BTL2	Understand
	PART-B		
1	What is conjunctive normal form? Illustrate and explain the procedure to convert sentences into conjunctive normal form with a neat example. Depict real images where it could be applied. (16)	BTL3	Apply

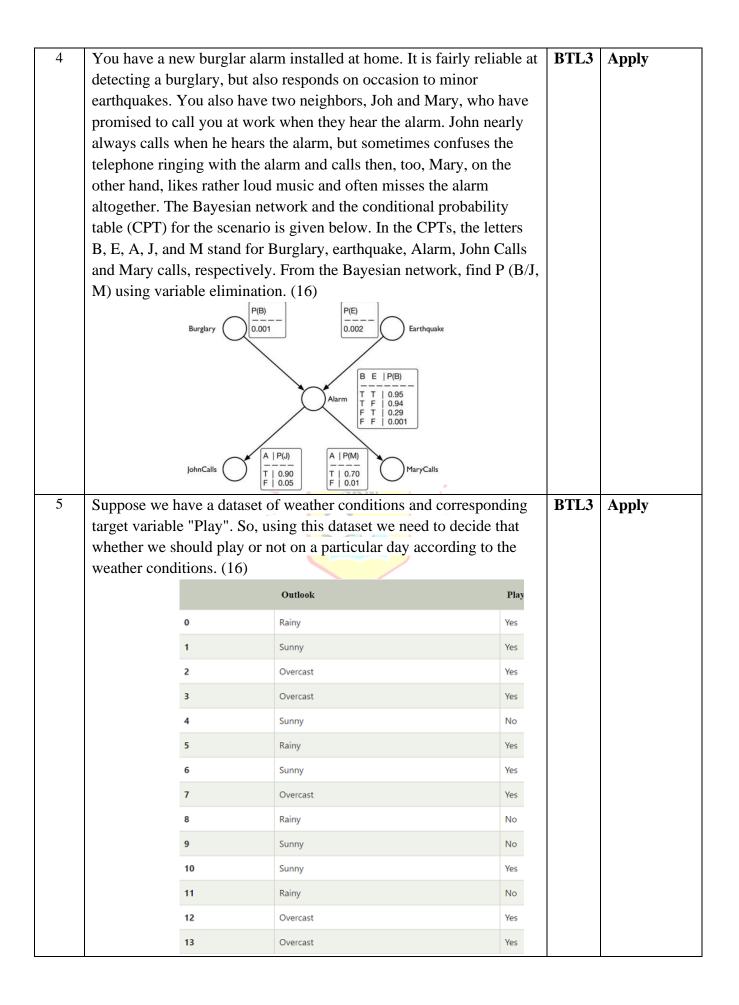
2	During a murder investigation, you have gathered some clues. Express them as propositions and solve the following scenario using laws of inference. The clues gathered are given below:	BTL3	Apply
	• If the knife is in the store room, then we saw it when we cleared the store room.		
	• The murder was committed at the basement or inside the apartment.		
	• If the murder was committed at the basement, then the knife is in the yellow dust bin.		
	 We did not see a knife when we cleared the store room. If the murder was committed outside the building, then we are unable to find the knife. 		
	 If the murder was committed inside the apartment, then the knife is in the store room. 		
3	Find: "Where is the knife?". (16)i. Brief on the concept of resolution and explain the propositional resolution algorithm. (7)	BTL3	Apply
	ii. Prove the following axioms using the resolution algorithm.(9)		
	 All hounds how! At night. Anyone who has any cats will not have any mice. 		
	 Light sleepers do not have anything which howls at night. John has either a cat or a bound. 		
	• (conclusion) If John is a light sleeper, then John does not have any mice.		
4	 Give the rules of inference in propositional logic. (9) Which rule of inference is used in each argument below? (7) Alice is a Math major and a CSI major. Therefore, Jerry is a math major. Jerry is a Math major and a CSI major. Therefore, Jerry is a math major. If it is rainy, then the pool will be closed. It is rainy. Therefore, the pool is closed. If it snows today, the university will close. The university is not 	BTL3	Apply
	closed today. Therefore, it did not snow today. If I go swimming, then I will stay in the sun too long. If I stay in the sun too long, then I will sunburn. Therefore, if I go swimming, then I will sunburn.		
5	Describe forward chaining and backward chaining algorithms in detail. Apply both the algorithms to prove that "West is a Criminal." (16)	BTL3	Apply

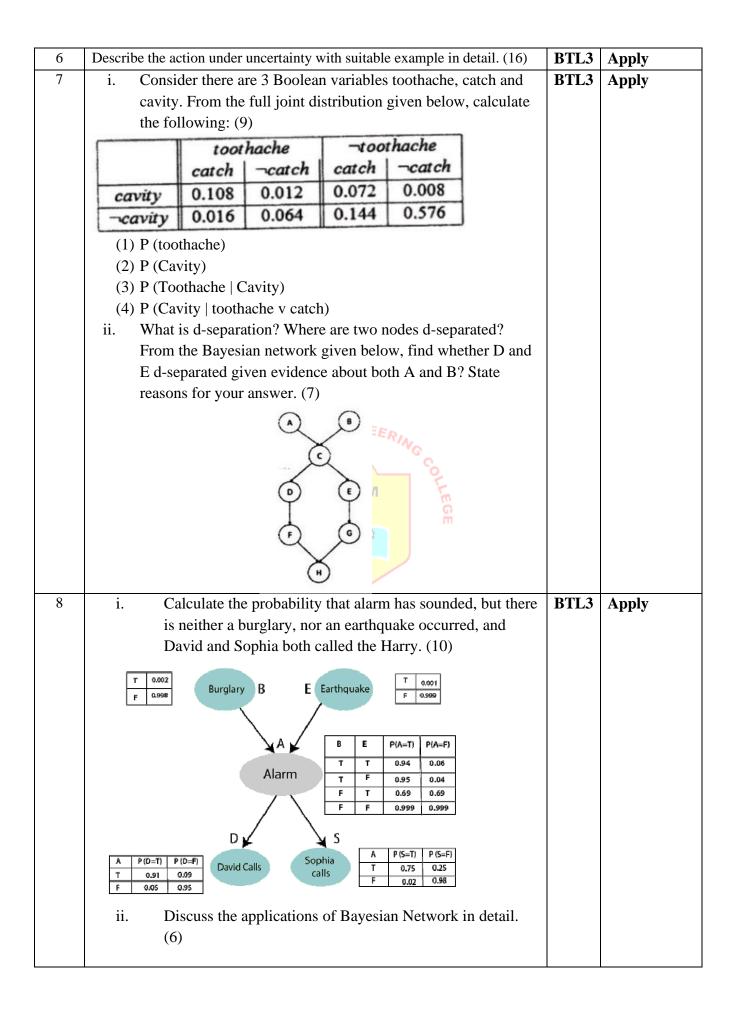
6	Express the following statements as predicates:	BTL3	Apply
	• All people who are not poor and are smart are happy		
	• Those people who read are not stupid.		
	• John can read and is wealthy.		
	• Happy people having exciting lives.		
	Skolemnize the above statements if required and prove the following by resolution: "Can anyone be found with an exciting life?" (Assume ~ stupid \equiv smart, wealthy \equiv ~poor). (16)		
7	Explain unification algorithm used for reasoning under predicate	BTL3	Apply
	logic with an example. (16)		
8	Explain the steps involved in knowledge engineering process. (16)	BTL3	Apply
9	What are logical connectives? Explain in detail. (9)	BTL4	Analyze
	Describe an algorithm for general propositional inference based on		
	model checking. (7)		
10	Discuss the Knowledge Engineering Process with proper	BTL4	Analyze
	illustration. Depict the concept of forward chaining. (16)		
11	Describe the procedure for converting a sentence into CNF with an	BTL4	Analyze
	example. (16)		
12	i. Explain standard quantifiers of first-order logic with	BTL4	Analyze
	examples. (9)		
	ii. Give the five logical connectives used to construct complex		
	sentences and give the formal grammar of propositional		
	logic. (7)		
13	Explain inferencing process in first order predicate logic. Apply	BTL4	Analyze
	both the algorithm to prove that "West is Criminal". (16)		
14	i. Write the algorithm for deciding entailment in propositional	BTL4	Analyze
	logic. (8)		
	ii. Explain the concepts of resolution in detail. (8)		
15	i. Explain the completeness of proof of resolution. (8)	BTL4	Analyze
	ii. What are the steps to convert FOL to Normal Form? Explain		
	each step. (8)		
16	Explain in detail the inference in the First order logic (FOL). (16)	BTL4	Analyze
17	i. Discuss the propositional theorem proving in detail. (6)	BTL4	Analyze
	ii. Explain the knowledge-based agents in detail with neat		
	sketch. (10)		

UNIT V KNOWLEDGE REPRESENTATION AND PLANNING

Ontological engineering – Categories and objects – Events – Mental objects and modal logic – Reasoning systems for categories – Reasoning with default information – Classical planning – Algorithms for classical planning – Heuristics for planning – Hierarchical planning – non-deterministic domains – Time, schedule, and resources – Analysis.

	PART – A		
Q.No	Questions	BT Level	Competence
1	Define Dampster-Shafer theory.	BTL1	Remember
2	Define Bayes Theorem.	BTL1	Remember
3	Define Uncertainty.	BTL1	Remember
4	State Bayes rule.	BTL1	Remember
5	What is reasoning?	BTL1	Remember
6	Define prior probability.	BTL1	Remember
7	State the types of approximation methods.	BTL1	Remember
8	What is causal networks?	BTL1	Remember
9	Why does uncertainty arise?	BTL1	Remember
10	What is Baye's rule? Mention its use.	BTL1	Remember
11	How are Bayesian networks represented?	BTL1	Remember
12	What is the purpose of relational probability models?	BTL1	Remember
13	Justify the purpose of Bayesian networks.	BTL2	Understand
14	Give the full specification of Bayesian Network.	BTL2	Understand
15	What do you mean by hybrid Bayesian network?	BTL2	Understand
16	What is the logic used in reasoning with uncertain information.	BTL2	Understand
17	State the types of inference in Bayesian network.	BTL2	Understand
18	Why does probabilistic reasoning necessary in AI?	BTL2	Understand
19	What is Naïve Bayes algorithm.	BTL2	Understand
20	What is the relationship between probability distribution and a Bayesian Network?	BTL2	Understand
21	What is meant by Joint probability and conditional probability.	BTL2	Understand
22	List the components of a Bayesian Network.	BTL2	Understand
23	Mention some applications of Bayes' theorem.	BTL2	Understand
24	What type of graph is used to represent a Bayesian Network?	BTL2	Understand
	PART-B		
1	Define uncertain knowledge, prior probability and conditional probability. State Bayes theorem. How is it useful for decision making under uncertainty. Explain belief network briefly. (16)	BTL3	Apply
2	i. Explain in detail about Bayesian Inference. (8)ii. Describe the Bayesian network in detail. (8)	BTL3	Apply
3	Describe the Naïve Bayes algorithm in detail with suitable example. (16)	BTL3	Apply





9	What is Bayesian network? Explain the method for constructing	BTL4	Analyze
	Bayesian networks. (16)		
10	i. What are the ways to understand the semantics of Bayesian	BTL4	Analyze
	Networks? (8)		
	ii. Discuss the exact inference in Bayesian networks. (8)		
11	How does direct sampling methods help in approximate inference?	BTL4	Analyze
12	Briefly explain exact inference in Bayesian Networks. (16)	BTL4	Analyze
13	Design a Bayesian belief network for the diagnosis of car's electrical	BTL4	Analyze
	system. (16)		
14	What is Bayesian Network? How Bayesian network is used to	BTL4	Analyze
	represent knowledge in uncertain domain. (16)		
15	Explain the method of performing exact inference in detail. (16)	BTL4	Analyze
16	Explain the method of performing approximate inference in detail. (16)	BTL4	Analyze
17.	i. Describe in detail about causal network. (8)	BTL4	Analyze
	ii. How to represent knowledge in an uncertain domain. (8)		



