

SRM VALLIAMMAI ENGINEERING COLLEGE

(An Autonomous Institution)

SRM Nagar, Kattankulathur – 603 203

DEPARTMENT OF ELECTRONICS AND INSTRUMENTATION ENGINEERING

QUESTION BANK



V SEMESTER

EC3568- DISCRETE TIME SIGNAL PROCESSING

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DEPARTMENT OF ELECTRONICS AND INSTRUMENTATION ENGINEERING



QUESTION BANK

SUBJECT: 1907502- DISCRETE TIME SYSTEMS AND SIGNAL PROCESSING

SEM / YEAR: V / III

UNIT-I CLASSIFICATION AND ANALYSIS OF SIGNALS

Classification of systems: Continuous , discrete, linear, causal, stable, dynamic, recursive, time variance-
Classification of signals: continuous and discrete, energy and power, Deterministic and Random, Periodic and Aperiodic; Mathematical representation of signals-Spectral density - Sampling techniques, quantization, quantization error, Nyquist rate, aliasing effect-Digital signal representation.

PART –A

Q.No	Questions	CO level	BT Level	Competence
1.	What are the classifications of discrete time systems?	CO1	BTL1	Remember
2.	Determine if the system is linear or not. $y(n) = x^2(n)$.	CO1	BTL2	Understand
3.	Define linear system.	CO1	BTL1	Remember
4.	What is casual system?	CO1	BTL1	Remember
5.	If $y[n] = x[n^2]$, is the system causal?	CO1	BTL2	Understand
6.	If $y(n) = x(n + 1) + x(n + 2)$, is the system causal?	CO1	BTL2	Understand
7.	Test if the system is stable or not. $y(n) = x(n)u(n)$.	CO1	BTL2	Understand
8.	Check if the system $y(n) = x(n)x(n - 1)$ is static.	CO1	BTL2	Understand
9.	Write the property of recursive and non-recursive systems.	CO1	BTL1	Remember
10.	What is time invariant system?	CO1	BTL1	Remember
11.	Find if the system is time invariant (or) not. $y(n) = x(-n)$.	CO1	BTL2	Understand
12.	What is an LTI system?	CO1	BTL1	Remember
13.	What is causality condition for LTI system?	CO1	BTL1	Remember
14.	Differentiate between Energy and Power signals.	CO1	BTL2	Understand
15.	What is a Deterministic signal?	CO1	BTL1	Remember
16.	Define periodic and non-periodic signal.	CO1	BTL1	Remember
17.	What is meant by spectral density?	CO1	BTL1	Remember
18.	State sampling theorem.	CO1	BTL1	Remember
19.	What is meant by sampling?	CO1	BTL1	Remember
20.	Define Quantization error.	CO1	BTL1	Remember
21.	List the sampling techniques.	CO1	BTL1	Remember

22.	State Nyquist rate.	CO1	BTL1	Remember
23.	Calculate the Nyquist rate for the following signal: $x(t) = 1 + 2\cos 1000\pi t - \sin 500\pi t$.	CO1	BTL2	Understand
24.	What is meant by digital signal representation	CO1	BTL2	Understand
PART – B				
1.	Test if the following systems are linear or not. (8+8) (i) $y(n) = ax(n) + bx(n - 1)$ (ii) $y(n) = \cos x(n)$	CO1	BTL5	Evaluate
2.	Test if the following systems are casual or not. (8+8) (i) $y(n) = x(n) + x^2(n - 1)$ (ii) $y(n) = x(n + 1) + 3x(n) + 5x(n - 1)$	CO1	BTL5	Evaluate
3.	Determine the stability for each of the following linear systems: (16) (i) $y(n) = x(2n)$ (ii) $y(n) = x(-n)$ (iii) $y(n) = e^{x(n)}$	CO1	BTL3	Apply
4.	Find whether the following systems are static (or) dynamic. (4+4+4+4) (i) $y(n) = x^2(n) + x(n - 1)$ (ii) $y(n) = x(2n)$ (iii) $y(n) = 2x^2(n)$ (iv) $y(n) = x^2(n + 2)$	CO1	BTL4	Analyze
5.	For each of the following systems, determine whether (or) not the system is time-invariant. (8+8) (i) $y(n) = nx(n)$ (ii) $y(n) = x(2n)$	CO1	BTL 4	Analyze
6.	Analyze whether the following system is linear, time varying, causal and stable $y(n) = nx^2(n)$. (16)	CO1	BTL3	Apply
7.	Distinguish the following with examples. (6+5+5) (i) Energy vs. power signal (ii) Deterministic and Random (iii) Periodic and Aperiodic	CO1	BTL3	Apply
8.	Determine whether each of the following signals is periodic. If the signal is periodic, specify its fundamental period. (8+8) (i) $x(n) = e^{j6\pi n}$ (ii) $x(n) = \cos \frac{\pi}{3}n + \cos \frac{3\pi}{4}n$.	CO1	BTL5	Evaluate
9.	Determine whether each of the following signals is periodic. If the signal is periodic, specify its fundamental period. (8+8) (i) $x(n) = e^{j\frac{3}{5}(n+\frac{1}{2})}$ (ii) $x(n) = \cos \frac{2\pi}{3}n$	CO1	BTL6	Create

10.	Define energy and power signal. Also examine whether the following signals are energy or power or neither energy nor power signals. (8+8) (i) $x_1(n) = \left(\frac{3}{2}\right)^n u(n)$ (ii) $x_2(n) = \cos\left(\frac{\pi}{6}n\right)$	CO1	BTL3	Apply
11.	Determine whether the following signals are energy or power or neither energy nor power signals. (8+8) (i) $x_1(n) = e^{j\left(\frac{\pi}{2}n + \frac{\pi}{4}\right)}$ (ii) $x_2(n) = e^{2n}u(n)$	CO1	BTL5	Evaluate
12.	Determine whether the following signals are energy or power or neither energy nor power signals. (8+8) (i) $x_1(n) = \left(\frac{1}{3}\right)^n u(n)$ (ii) $x_2(n) = \sin\left(\frac{\pi}{4}n\right)$	CO1	BTL3	Apply
13.	What are the basic operations of signals? Illustrate with an example. (16)	CO1	BTL4	Analyze
14.	Consider the analog signal $x(t) = 3 \cos 100\pi t$ (16) (i) Determine the minimum sampling rate required to avoid aliasing. (ii) If the signal is sampled at the rate $F_s = 200\text{Hz}$, what is the discrete time signal obtained after sampling.	CO1	BTL5	Evaluate
15.	Define Nyquist rate. Compare the merits and demerits of performing sampling using impulse, Natural and Flat-top sampling techniques. (16)	CO1	BTL3	Apply
16.	(i) Describe about spectral density and aliasing effect. (8) (ii) Discuss about the process of quantization and describe how quantization error can be minimized? (8)	CO1	BTL4	Analyze
17.	Summarize about the different type of Digital signal representation with example. (16)	CO1	BTL4	Analyze

UNIT-II DISCRETE TIME SYSTEM ANALYSIS

SYLLABUS

Z-transform and its properties, inverse z-transforms; difference equation – Solution by z transform, application to discrete systems - Stability analysis, frequency response – Convolution – Discrete Time Fourier transform , magnitude and phase representation.

PART –A

Q	Questions	CO level	BT Level	Competence
1.	Define z-transform.	CO2	BTL1	Remember
2.	What is the region of convergence (ROC) in Z-transform?	CO2	BTL1	Remember
3.	What are the properties of Region of convergence?	CO2	BTL1	Remember

4.	Determine the Z-transform the following finite duration signal $x(n) = \{1,2, 3, 4\}$.	CO2	BTL2	Understand
5.	State initial value theorem of Z transform.	CO2	BTL1	Remember
6.	Explain the multiplication property of the z-transform.	CO2	BTL1	Remember
7.	What is the Z-transform of $\delta(n)$?	CO2	BTL2	Understand
8.	What is the difference between bilateral and unilateral Z-transform?	CO2	BTL2	Understand
9.	Calculate the Z-transform of $x(n) = a^n u(n)$.	CO2	BTL2	Understand
10.	What is the inverse Z-transform? Name two methods to compute it.	CO2	BTL1	Remember
11.	State the condition for stability using the Z-transform	CO2	BTL2	Understand
12.	List the methods of evaluating inverse Z-transform.	CO2	BTL1	Remember
13.	Find the z-transform of digital impulse and digital ramp signal.	CO2	BTL2	Understand
14.	Write the conditions to define stability in ROC.	CO2	BTL2	Understand
15.	Define system function.	CO2	BTL1	Remember
16.	Give the system function H(z) for $y(n) = x(n) + 2x(n - 1) - 4x(n - 2) + x(n - 3)$.	CO2	BTL2	Understand
17.	State the relation between DTFT and Z-transform.	CO2	BTL1	Remember
18.	State time reversal property of the Z-transform.	CO2	BTL1	Remember
19.	State the time-shifting property of Z-transform.	CO2	BTL1	Remember
20.	Define Fourier transform of a sequence and give its symmetry property.	CO2	BTL1	Remember
21.	Define discrete-time Fourier transform pair for a discrete sequence.	CO2	BTL2	Understand
22.	Determine the DTFT of the sequence $x(n) = \{1, -1, 1, -1\}$.	CO2	BTL2	Understand
23.	What are the properties of Fourier transform of a discrete –time aperiodic sequence?	CO2	BTL1	Remember
24.	Express the relationship between s-plane and z-plane.	CO2	BTL2	Understand
PART – B				
1.	State and prove any five properties of z transform. (16)	CO2	BTL3	Apply
2.	Find the Z transform of $x(n) = n^2 u(n)$. (16)	CO2	BTL3	Apply
3.	Determine the z transform and its ROC of the discrete time signal $x(n) = a^n u(n) + b^n u(-n - 1)$ (16)	CO2	BTL3	Apply
4.	Find Z-transform and ROC of the causal sequence. (8+8) (i) $x(n) = \{1,0,3, -1,2\}$ (ii) $x(n) = \{1, -2,1,3,4\}$	CO2	BTL4	Analyze
5.	Consider the signal x(n) is given by $x(n) = \left(\frac{1}{2}\right)^n u(n) + \left(\frac{-1}{4}\right)^n u(n)$. Determine X(z) and ROC. (16)	CO2	BTL4	Analyze
6.	Find the Z-transform of the signals (8+8) (i) $x(n) = (\sin\omega_0 n)u(n)$. (ii) $x(n) = (\cos\omega_0 n)u(n)$.	CO2	BTL4	Analyze
7.	Find the inverse z transforms of (16) $X(z) = \frac{z+0.2}{(z+0.5)(z-1)}$ ROC $ z > 1$ using long division method.	CO2	BTL3	Apply

8.	Determine the inverse z transform of $X(z) = \frac{1+3z^{-1}}{1+3z^{-1}+2z^{-2}}$ ROC $ z > 2$.	(16)	CO2	BTL3	Apply
9.	Using residue method find the inverse Z transform $X(z) = \frac{z+1}{(z+0.2)(z-1)}$ ROC $ z > 1$	(16)	CO2	BTL4	Analyze
10.	Find the inverse Z transform of $X(z) = \frac{1}{1-3z^{-1}+2z^{-2}}$ using convolution method.	(16)	CO2	BTL3	Apply
11.	Find the impulse response of the system described by difference equation using z-transform. $y(n) - 3y(n-1) - 4y(n-2) = x(n) + 2x(n)$	(16)	CO2	BTL4	Analyze
12.	Find the response of the causal system $y(n) - y(n-1) = x(n) + x(n-1)$ to the input $x(n) = u(n)$. Test its stability.	(16)	CO2	BTL5	Evaluate
13.	Convolute the following two sequences $x_1(n) = \{0,1,4,-2\}$ and $x_2(n) = \{1,2,2,2\}$.	(16)	CO2	BTL4	Analyze
14.	Find the linear convolution of $x(n) = \{1,2,3,4,5,6,7\}$ with $h(n) = \{2,4,6,8\}$.	(16)	CO2	BTL5	Evaluate
15.	State and Prove the linearity and frequency shifting property of DTFT.	(16)	CO2	BTL3	Apply
16.	Determine the frequency response $H(e^{j\omega})$ for the given system and plot magnitude and phase response, $y(n) + \frac{1}{4}y(n-1) = x(n) + x(n-1)$.	(16)	CO2	BTL4	Analyze
17.	Evaluate the frequency response of the system described by system function $H(z) = 1/(1 - 0.5z^{-1})$	(16)	CO2	BTL5	Evaluate

UNIT-III DISCRETE FOURIER TRANSFORM & COMPUTATION

SYLLABUS

DFT- properties, magnitude and phase representation – Computation of DFT using FFT algorithm – DIT & DIF
FFT using radix 2– Butterfly structure.

PART –A

Q	Questions	CO level	BT Level	Competence
1.	State circular frequency shift property of DFT.	CO3	BTL1	Remember
2.	What is zero padding?	CO3	BTL1	Remember
3.	Find the discrete Fourier transform for $\delta[n]$.	CO3	BTL2	Understand
4.	Estimate the DFT of the signal $x(n) = a^n$	CO3	BTL2	Understand
5.	Evaluate the 4-point DFT of the sequence $x(n) = \{1,1,-2,-2\}$.	CO3	BTL2	Understand
6.	Evaluate the 4-point DFT of the sequence $x(n) = \{1,1,0,0\}$.	CO3	BTL2	Understand
7.	State Parseval's relation for DFT.	CO3	BTL1	Remember
8.	Compute the number of multiplications and additions for 32-point DFT and FFT.	CO3	BTL2	Understand
9.	What is the main advantage of FFT?	CO3	BTL1	Remember
10.	State circular convolution.	CO3	BTL1	Remember
11.	Obtain the circular convolution of the following sequences $x(n) = \{1,2,1\}$ $h(n) = \{1,-2,2\}$.	CO3	BTL2	Understand

12.	What is FFT?		CO3	BTL1	Remember
13.	Draw the basic butterfly flow graph for the computation in the DIT FFT algorithm.		CO3	BTL1	Remember
14.	What is meant by radix-2 FFT?		CO3	BTL1	Remember
15.	Draw the flow graph of a 4-point DFT by applying radix-2 DIF-FFT algorithm.		CO3	BTL1	Remember
16.	Draw the flow graph of a 4-point DFT by applying radix-2 DIT-FFT algorithm.		CO3	BTL1	Remember
17.	What is the basic operation in DIT algorithm?		CO3	BTL1	Remember
18.	Draw the basic butterfly diagram for DIF algorithm.		CO3	BTL1	Remember
19.	Compare DIT radix-2 FFT and DIF radix-2 FFT.		CO3	BTL2	Understand
20.	What are the applications of FFT algorithm?		CO3	BTL1	Remember
21.	In eight point decimation in time (DIT), calculate the gain of the signal path that goes from $x(7)$ to $x(2)$.		CO3	BTL2	Understand
22.	Explain how butterfly structure is helpful in DFT computation?		CO3	BTL2	Understand
23.	Summarize the information we get from magnitude and phase representation.		CO3	BTL1	Remember
24.	Discuss about “in-place computation” in FFT algorithm		CO3	BTL2	Understand
PART –B					
1.	State and prove any four properties of DFT.	(16)	CO3	BTL3	Apply
2.	Find the DFT of a sequence. $x[n] = \begin{cases} 1 & \text{for } 0 \leq n \leq 2 \\ 0 & \text{otherwise} \end{cases} \quad \text{for } N = 4.$ Plot its magnitude response.	(16)	CO3	BTL4	Analyze
3.	Determine the DFT of the sequence $x(n) = \begin{cases} \frac{1}{4}, & \text{for } 0 \leq n \leq 2 \\ 0, & \text{otherwise} \end{cases}$	(16)	CO3	BTL4	Analyze
4.	Find the circular convolution of two finite duration sequences. $x_1(n) = \{1, -1, -2, 3, -1\}, \quad x_2(n) = \{1, 2, 3\}$	(16)	CO3	BTL5	Evaluate
5.	By means of DFT and IDFT, determine the sequence $x(n)$ corresponding to the circular convolution of sequences $x_1(n)$ and $x_2(n)$ given by $x_1(n) = \{1, 2, 3, 4\} \quad x_2(n) = \{1, 1, 2, 2\}.$	(16)	CO3	BTL5	Evaluate
6.	Find the DFT of a sequence $x[n] = \{1, 1, 1, 1, 1, 1, 1, 1\}$ using Decimation- in- Time (DIT) algorithm.	(16)	CO3	BTL3	Apply
7.	Find the DFT of a sequence $x[n] = \{1, 2, 3, 4, 4, 3, 2, 1\}$ using Decimation- in- Time (DIT) algorithm.	(16)	CO3	BTL3	Apply
8.	Derive and draw the butterfly diagram for computing 8-point DFT of a sequence $x(n)$ using DIF FFT algorithm.	(16)	CO3	BTL4	Analyze
9.	Derive and draw the butterfly diagram for computing 8-point DFT of a sequence $x(n)$ using DIT FFT algorithm.	(16)	CO3	BTL4	Analyze
10.	Find the DFT of a sequence $x[n] = \{1, 0, 0, 0, 0, 0, 0, 0\}$ using Decimation- in- Time (DIT) algorithm.	(16)	CO3	BTL3	Apply
11.	Compute the 4-point DFT of the sequence $x(n) = \{0, 1, 2, 3\}$ using DIT and DIF algorithm.	(16)	CO3	BTL4	Analyze

12.	Find the DFT of a sequence $x[n] = \{1,2,3,4,4,3,2,1\}$ using Decimation- in-Frequency (DIF) algorithm. (16)	CO3	BTL4	Analyze
13.	Find the IDFT of the sequence $X(k) = \{4,1 - j2.414,0,1 - j0.414,0,1 + j0.414,0,1 + j2.414\}$ using DIF algorithm. (16)	CO3	BTL3	Apply
14.	An 8 point sequence is given by $x(n) = \{2,2,2,2,1,1,1,1\}$, compute 8 point DFT of $x(n)$ by radix 2 DIT FFT. Also analyze its response with respect to magnitude and space spectrum. (16)	CO3	BTL4	Analyze
15.	Consider the sequences: $x_1(n) = \{0,1,2,3,4\}$, $x_2(n) = \{0,1,0,0,0\}$ and $s(n) = \{1,0,0,0\}$ (i) Determine a sequence $y(n)$ so that $Y(k) = X_1(k)X_2(k)$ (ii) Is there a sequence $x_3(n)$ such that $S(k) = X_1(k)X_3(k)$. (8+8)	CO3	BTL5	Evaluate
16.	Describe the need for Bit reversal and the Butterfly structure. For a sequence $x(n) = \{4,3,2,1, -1,2,3,4\}$ obtain the 8 point FFT computation using DIT method. (16)	CO3	BTL6	Create
17.	Given $x(n) = n + 1$, and $N = 8$, find $X(k)$ using DIT FFT algorithm. (16)	CO3	BTL3	Apply

UNIT-IV DESIGN OF DIGITAL FILTERS

SYLLABUS

FIR & IIR filter realization – Parallel & cascade forms. FIR design: Windowing Techniques –Need and choice of windows – Linear phase characteristics. Analog filter design –Butterworth and Chebyshev approximations; digital design using impulse invariant and bilinear transformation Warping, pre warping-Frequency transformation

PART –A

Q. No	Questions	CO level	BT Level	Competence
1.	Summarize, why digital filters are more useful than analog filters?	CO4	BTL1	Remember
2.	Distinguish the IIR and FIR filter.	CO4	BTL2	Understand
3.	What are the different types of structures for realization of IIR systems?	CO4	BTL1	Remember
4.	Write the advantages and disadvantages of FIR filters.	CO4	BTL1	Remember
5.	How one can design digital filters from analog filters?	CO4	BTL2	Understand
6.	Relate under what conditions an FIR filter will exhibit linear phase response.	CO4	BTL2	Understand
7.	What are the different types of structures for realization of FIR systems?	CO4	BTL1	Remember
8.	What is bilinear transformation?	CO4	BTL1	Remember
9.	Point out the limitation of using rectangular window in FIR filter design.	CO4	BTL2	Understand
10.	Give Hamming window function.	CO4	BTL1	Remember
11.	What is Gibb's phenomenon?	CO4	BTL1	Remember

12.	What is the main disadvantage of direct-form realization?	CO4	BTL1	Remember
13.	Discuss about the pass band and stop band characteristics of Butterworth filter.	CO4	BTL2	Understand
14.	List the properties of Chebyshev filter.	CO4	BTL2	Understand
15.	Write the advantages and disadvantages of digital filters.	CO4	BTL1	Remember
16.	Name the methods that convert the transfer function of analog filter into digital filter.	CO4	BTL1	Remember
17.	Give the mapping relation for mapping of s-plane to z-plane in bilinear transformation.	CO4	BTL1	Remember
18.	What is warping effect? Examine its effect on frequency response?	CO4	BTL2	Understand
19.	What is pre-warping? Conclude what happens, if pre-warping is not employed?	CO4	BTL1	Remember
20.	What is impulse invariant transformation?	CO4	BTL1	Remember
21.	Is the given transfer function $H(z) = \frac{1+0.8Z^{-1}}{1-0.9Z^{-1}}$ represents low pass filter or high pass filter. Justify the answer	CO4	BTL2	Understand
22.	Draw the frequency response of N-point rectangular window.	CO4	BTL1	Remember
23.	Analyze the need for employing window for designing FIR filter?	CO4	BTL2	Understand
24.	How do you analyze in selecting the type of filter (IIR/FIR) for an application?	CO4	BTL2	Understand

PART -B

1.	Obtain the direct form I and direct form II realization for the system. $y(n) = -0.1y(n-1) + 0.2y(n-2) + 3x(n) + 3.6x(n-1) + 0.6x(n-2)$. (16)	CO4	BTL3	Apply
2.	Obtain the cascade form and parallel form realization for the system. $y(n) = -0.1y(n-1) + 0.2y(n-2) + 3x(n) + 3.6x(n-1) + 0.6x(n-2)$. (16)	CO4	BTL3	Apply
3.	Show the realization for the following system using cascade form. (16) $H(z) = \frac{\left(1 + \frac{1}{3}z^{-1}\right)}{\left(1 - \frac{3}{42}z^{-1} + \frac{1}{8}z^{-2}\right)}$	CO4	BTL5	Evaluate
4.	Realize the system given by difference equation $y(n) = 0.1y(n-1) + 0.72y(n-2) - 0.252x(n-2)$ in parallel form. (16)	CO4	BTL4	Analyze
5.	(i) Determine the direct form realization of system function. $H(z) = 1 + 2z^{-1} - 3z^{-2} - 4z^{-3} + 5z^{-4}$ (8) (ii) Determine the cascade form realization of system function. $H(z) = (1 + 2z^{-1} - z^{-2})(1 + z^{-1} - z^{-2})$ (8)	CO4	BTL3	Apply
6.	Show the realization for the following system using cascade and parallel structures (16) $H(z) = \frac{\left(1 + \frac{1}{4}z^{-1}\right)}{\left(1 + \frac{1}{2}z^{-1}\right)\left(1 + \frac{1}{2}z^{-1} + \frac{1}{4}z^{-2}\right)}$	CO4	BTL4	Analyze

7.	Design a filter with desired frequency response $H_d(e^{j\omega}) = e^{-j3\omega} \text{ for } -\frac{\pi}{4} \leq \omega \leq \frac{\pi}{4}$ $= 0 \text{ for } -\frac{\pi}{4} \leq \omega \leq \pi$ Using a Hamming window for N=7. (16)	CO4	BTL3	Apply
8.	Design an ideal low pass filter with a frequency response $H_d(e^{j\omega}) = \begin{cases} 1 & \text{for } -\frac{\pi}{2} \leq \omega \leq \frac{\pi}{2} \\ 0 & \text{for } \frac{\pi}{2} \leq \omega \leq \pi \end{cases}$ Find H(z) and the filter coefficients for N=11. (16)	CO4	BTL4	Analyze
9.	Using rectangular window technique design a LPF with pass band gain of unity, cut-off frequency of 1000Hz and working sampling frequency of 5kHz. The length of impulse is 7. (16)	CO4	BTL5	Evaluate
10.	Given the specifications $\alpha_p = 3dB$, $\alpha_s = 10dB$, $f_p = 1kHz$ and $f_s = 2kHz$. Determine the order of the filter using Chebyshev approximation. Find H(s). (16)	CO4	BTL3	Apply
11.	Design an Analog Butter Worth filter that has -2dB pass band attenuation at a frequency of 20rad/sec and at least -10dB stop band attenuation at 30 rad/sec. (16)	CO4	BTL5	Evaluate
12.	(i) Illustrate the bilinear transformation method of obtaining digital filter from analog filter. (8) (ii) Illustrate impulse invariant method of designing IIR filter. (8)	CO4	BTL4	Analyze
13.	Using impulse variance method with T=1 Sec. Compute H(z) if $H(s) = \frac{1}{s^2 + \sqrt{2}s + 1}$ (16)	CO4	BTL4	Analyze
14.	Apply bilinear transformation to $H(s) = \frac{2}{(s+1)(s+2)}$ with T=1sec and compute H(z). (16)	CO4	BTL3	Apply
15.	Apply impulse variance method to $H(s) = \frac{2}{(s+1)(s+2)}$ with T=1sec and compute H(z). (16)	CO4	BTL3	Apply
16.	Convert the following analog transfer function into digital by applying impulse invariant technique with sampling period T=1 sec $H(z) = s + \frac{1}{(s+3)(s+5)}$ (16)	CO4	BTL4	Analyze
17.	Design a Butterworth filter using the Impulse invariance method for the following specifications. $0.8 \leq H(e^{j\omega}) \leq 1 \quad 0 \leq \omega \leq 0.2\pi$ $ H(e^{j\omega}) \leq 0.2 \quad 0.6\pi \leq \omega \leq \pi$ (16)	CO4	BTL3	Apply

UNIT-V DIGITAL SIGNAL PROCESSOR

SYLLABUS

Introduction –Architecture of DSP processor – Features-Addressing formats-Functional modes-Introduction to commercial processor.

PART –A

Q.N o	Questions	CO level	BT Level	Competen ce
1.	What is a Digital Signal Processor (DSP)?	CO5	BTL1	Remember
2.	List any two applications of DSP.	CO5	BTL2	Understand
3.	Define the term real-time processing.	CO5	BTL1	Remember
4.	What is the difference between a general-purpose processor and a DSP?	CO5	BTL1	Remember
5.	Why are DSPs preferred over microcontrollers for signal processing?	CO5	BTL2	Understand
6.	Mention two features of DSP architecture.	CO5	BTL2	Understand
7.	What is the role of the Multiply-Accumulate (MAC) unit in DSP?	CO5	BTL2	Understand
8.	Define pipelining in DSP.	CO5	BTL1	Remember
9.	What is the function of the program memory in a DSP?	CO5	BTL2	Understand
10.	Write about circular buffer in DSP.	CO5	BTL1	Remember
11.	What is modulo addressing?	CO5	BTL2	Understand
12.	Mention any two special addressing modes used in DSPs.	CO5	BTL1	Remember
13.	What is the purpose of auxiliary registers in DSP?	CO5	BTL2	Understand
14.	Define Harvard architecture.	CO5	BTL1	Remember
15.	What is the role of the Multiply-Accumulate (MAC) unit in DSP?	CO5	BTL1	Remember
16.	Define pipelining in DSP.	CO5	BTL2	Understand
17.	Give the function of the program memory in a DSP?	CO5	BTL1	Remember
18.	What is meant by instruction pipelining?	CO5	BTL2	Understand
19.	Define parallel processing in DSP.	CO5	BTL1	Remember
20.	What is register file in DSP architecture?	CO5	BTL2	Understand
21.	Give the various factor influence selection of DSPs.	CO5	BTL2	Understand
22.	List the are applications of DSPs.	CO5	BTL1	Remember
23.	List the classification of digital signal processors.	CO5	BTL1	Remember
24.	Why Linear and Time Invariant(LTI) systems are widely used in digital signal processing applications	CO5	BTL2	Understand

PART –B

1.	Summarize about the types of DSP processors .	(16)	CO5	BTL4	Analyze
2.	(i) Elaborate about the classifications of DSP processors . (ii) Summarise about the applications of PDSPS.	(8) (8)	CO5	BTL4	Analyze
3.	Describe the different applications of Programmable (PDSP)?	(16)	CO5	BTL4	Analyze
4.	Explain about the following (i)Van Neuman Architecture (ii) Harvard Architecture	(8) (8)	CO5	BTL3	Apply
5.	Explain about VLIW architecture and also give advantages and disadvantages	(16)	CO5	BTL3	Apply

6.	Explain about (i) Multiply Accumulate unit (MAC) unit (ii) Pipeling in DSP	(8+8)	CO5	BTL4	Analyze
7.	Draw and explain the architecture of TMS320C50 processor .	(16)	CO5	BTL3	Apply
8.	Describe about the addressing modes of TMS320C50 processor with example .	(16)	CO5	BTL4	Analyze
9.	Explain about the instruction set of TMS320C50 processor with example.	(16)	CO5	BTL4	Analyze
10.	Draw and explain the architecture of TMS320C54x processor.	(16)	CO5	BTL3	Apply
11.	Explain pipelining (stages and importance) and compare Von Neumann vs Harvard architectures.	(16)	CO5	BTL4	Analyze
12.	Describe with a neat diagram the generic internal architecture of a DSP processor and explain the function of the main components.	(16)	CO5	BTL3	Apply
13.	Summarize the onchip peripherals of TMS320C54x processor.	(16)	CO5	BTL3	Apply
14.	(i) Explain the functional blocks of TMS320C50 CPU.	(8)	CO5	BTL4	Analyze
	(ii) List any six major features of digital signal processors.	(8)	CO5		
15.	Design a DSP based system for the process of audio signals in an audio recorder system.	(16)	CO5	BTL4	Analyze
16.	Elaborate on Radar signal processing using a DSP Processor.	(16)	CO5	BTL5	Evaluate
17.	Describe about the different commercial DSP Processors in details.	(16)	CO5	BTL4	Analyze

